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COMPUTATION OF POWER SPECTRAL  
DENSITIES AND CORRELATIONS  
USING DIGITAL FFT TECHNIQUES

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## 1. INTRODUCTION

Spectral measurements are frequently required in fluid mechanics applications. Traditionally they have been made using analog techniques. With the development of the Fast Fourier Transform algorithms in the mid 1960's, digital techniques have evolved which enable power spectral densities and correlation functions to be calculated with costs much less than were previously possible. This report is intended to describe the Fast Fourier Transform algorithms available at Colorado State University, outline some of the difficulties encountered in using these algorithms, and provide a brief description of actual computer programs being used for spectral analysis on the CDC 6400 computer.

## 2. EXISTING FFT ROUTINES AT CSU

There are presently a number of computer programs used at CSU which use available FFT routines. Two FFT programs are being used extensively by the Fluid Mechanics and Wind Engineering group. These are FOR2D and FOURT, both a part of the IBM Contributed Program Library. FOURT (IBM Contributed Program No. 360D-13.4001) is presently on the system Fortran library (FTNLIB). FOR2D (IBM Contributed Program No. 360D-13.4006) is usually stored on a permanent file. For CSU users, a deck or access to this permanent file may be obtained by contacting Robert Akins or Dr. J. Peterka. The major difference between these two programs is that FOURT is written to use data located in the core of the computer and FOR2D is written to use data located on an external storage device. More detailed comments on these two specific subroutines appear in later sections.

### 3. SINGLE CHANNEL FORWARD/INVERSE TRANSFORM

Two separate uses of the FFT will be described; (1) calculation of a power spectral density from a time series and (2) transformation of a power spectral density to obtain an autocorrelation function. An explanation of the details of these types of calculations can be found in Bendat and Piersol (1). It will be assumed in the following discussions that the reader is familiar with this reference or an equivalent text.

The single-channel forward/inverse transform is perhaps the most straightforward application of the FFT, and is a good starting point for someone beginning to work with the FFT. A useful exercise is to select a known fourier transform pair and to perform the same transform using the FFT. An example utilizing this type approach will be discussed in order to illustrate usage of subroutine FOURT. Appendix A1 contains a program listing of subroutine FOURT. A short section of comments appears at the beginning of the listing and explains the calling parameters and some basic aspects of usage. Use of the program can be understood without a detailed understanding of the details of the program itself.

The example transform pair to be used consists of  $R(t) = e^{-t}$ ,  $t \geq 0$  and its inverse fourier transform  $G(\omega) = \frac{4}{1+\omega^2}$ ,  $\omega \geq 0$ . Such an  $R$  function is often used to represent the autocorrelation function of a fluctuating velocity signal and is not only an easy function to deal with, but also is of some physical significance. A sample program (Program CHECK) which was written to take a forward and inverse fourier transform is listed in Appendix B1. The following discussion

will be based upon output from that program. References to the program will be by line number of the listing in the appendix.

The program was written to calculate a selected number of values of the function  $R(t)$  at a time step specified by an input parameter. This array of values of  $R(t)$ , called  $D$  in the program, is reflected prior to performing the forward transform. This reflection is an important operation which is not adequately discussed in most texts.

It is needed to satisfy continuous, even-function characteristics of the transform. In using a digital transform technique, one assumes

that the data record is of infinite length. In order to create a record which resembles an infinite record, the function to be transformed is reflected about its endpoint, creating a symmetric, even, continuous function. A schematic of this reflection and the resulting periodic function is shown in Figure 1. Note that the function is one

$\Delta T$  increment short of returning to the zero-time value of one at the time position  $2N \Delta T$ . This occurs because the reflection point is really at the  $N(\Delta T+1)$  point rather than precisely on the  $N\Delta T$  point as might be expected. The effect of not reflecting  $R$  prior to the transform is shown in Figure 2. In other words, the reflection should be done about a zero lag time, such that  $R(\tau) = R(-\tau)$  so that the reflected correlation function is even. If there are  $2N$  total points,  $N$  prior to reflection, then  $R(N+I) = R(N+2-I)$  for  $2 \leq I \leq N$ .

This scheme of reflection will result in the point  $R(N+1)$  not being defined. Since a correlation is normally small at the maximum lag time, it is easiest to let  $R(N+1)$  equal  $R(N)$ . The reflection in program check is performed in lines 35-40.

After the data has been reflected and the  $D(2,I)$ 's set to zero, subroutine FOURT is called in line 43. It is necessary to create  $D$  as a two-dimensional array because the input to FOURT is complex. In many applications of these techniques only real signals are dealt with and the complex arithmetic capabilities of the program are not used. In these cases the fifth calling parameter of FOURT is set equal to zero indicating a real input only. It is important to understand the difference between NUMBER and NUMBE2. NUMBER as used in the program is the number of points in the unreflected R function. NUMBE2 is twice NUMBER or the length of the reflected R function.

After FOURT has been called, the output must be multiplied by a scaling factor in order to obtain the correct  $G$ . This factor for FOURT is  $2 * \text{DELTAT}$  where DELTAT is the timestep of R. This multiplication is carried out in line 52 of Program Check. The  $G$  function returned from FOURT has data uniformly spaced in frequency with the data points at  $f = n / (\text{NUMBER} * \text{DELTAT})$ ,  $n = 0, \text{NUMBER}-1$ .

Prior to performing the inverse transform, G is also reflected. In addition to reflecting  $G$ , the imaginary part of the  $D$  array is set to zero. Normally small values will appear in this position of the array during a transform and the inverse transform will be more accurate if the imaginary ( $D(2,I)$ ) part of the  $D$  array is forced to zero. These operations are carried out in lines 57 to 65.

An inverse transform is performed to obtain the original  $R(t)$ . Again the output of FOURT must be multiplied by a constant. For the inverse transform, this factor is  $1 / (4 * \text{NUMBER} * \text{DELTAT})$ . The product of the factors for the forward and inverse transforms is  $1 / (2 * \text{NUMBER})$

or  $1/\text{NUMBER2}$ . This agrees with the factor given in the write-up of FOURT in Appendix A1.

Several examples using the test functions  $R$  and  $G$  will now be discussed. A number of different experiments were conducted to determine the effect of the total time and the time increment on the accuracy of the results. In the tables and plots that follow,  $R^*$  will denote the recovered  $R$  function after a forward and an inverse transform.

Figure 3 is a comparison of  $G$  for various values of NUMBER, the total number of points, and DELTAT, the time step between points. These variables were selected to result in all of the  $R$ 's being defined for the same total time. This plot is only for the higher frequencies; below  $\omega = 3$ , all of the cases tested agree. The N's on the plot are for the unreflected data. It can be seen that as NUMBER increases and DELTAT decreases the region over which the transform is accurate increases. For NUMBER equal to 2048, the results are very close to the actual function  $G$  for the entire range plotted. At higher frequencies, even the case for NUMBER equal to 2048 will deviate from the actual values.

A comparison of  $R^*$  for the same cases is shown in Figure 4.  $R^*$  is the initial function  $R$  after having been subjected to both a forward and inverse transform. In this case virtually all values of NUMBER yield an acceptable value for  $R^*$ .

The central processor (Cp) times required for the various values of NUMBER2 are shown in Figure 5. It can be seen that there is an almost linear increase in Cp time with increasing NUMBER2. These times are for the actual transform only; any multiplication or other

manipulations with the data would increase them. These test cases were run under the Scope 3.3.14 on the CSU CDC 6400 computer.

In summary, the FFT can be used rapidly and economically to perform a digital fourier transform of known data. Care must be taken to insure the data are reflected properly prior to the transform and that the appropriate factors are used after the transform. A user with no experience with FFT is strongly urged to experiment with this type of application prior to attempting to obtain a spectrum directly from digital data.

#### 4. CALCULATION OF A POWER SPECTRAL DENSITY FROM A TIME SERIES

Another valuable application of the FFT is the calculation of a power spectral density function from a time series. A detailed explanation of this process is given in Chapter 9 of Bendat and Piersol (1) or in Chapter 6 of Enochson and Ontes (2). The basic equations used are straightforward and apply to any FFT routine.

There is one significant difference between the procedures outlined in these references and the procedure recommended in this report.

This difference has to do with the addition of zeros to the initial time series to avoid having a distorted autocorrelation function as discussed on pages 312-314 of Bendat and Piersol (1). If one uses the reflection techniques described in Section 3 in obtaining an autocorrelation function from a power spectral density, the addition of zeros to the initial time series is unnecessary. This results in a significant advantage in that the same time series can be placed in a data array half the size required if the technique described in Bendat and Piersol (1) is used. In other words if a time

series of data consisting of 2000 points was to be examined using standard procedures, an array of length 4000 would be required. If the reflection technique was used, the required array length would only be 2000 and there would be a savings in core of 50 percent. In most cases the size of the data array is limited by the available core of the computer, and therefore the ability to use a smaller array can be a significant advantage.

At this point nomenclature comparable to that in Bendat and Piersol will be introduced to make the following discussions easier to follow. Denote the time series by  $x_n(t)$ ,  $n = 1, N$ , the fourier transform of this time series by  $X(f_n, N)$   $n = 1, N$ , and the spectral density function of the time series  $x_n$  by  $\tilde{G}_x(f_n)$ ,  $n = 1, N$ .  $f_n = (n-1)/T$  where  $T = N \Delta t$ .  $\Delta t$  is the time increment of the initial time series.

In terms of these variables, a technique for computation of power spectral densities is:

1. Truncate the data sequence or add zeros such that  $N$  is a power of 2. In most cases, the data should be taken to provide  $N$  data values without adding any zeros.
2. Taper this sequence using a cosine taper window. This process is discussed in Bendat and Piersol (1), pp. 322-324.
3. Compute  $X(f_n, N)$  using a FFT routine.
4. Compute  $\tilde{G}_x(f_n)$  using the equation 
$$\tilde{G}_x(f_n) = \frac{2 \cdot \Delta t}{.875 \cdot N} |X_k|^2$$
5. Smooth  $\tilde{G}_x(f_n)$  using either frequency or segment averaging.

Frequency averaging averages together several values of  $\tilde{G}_x$  from one transform about some value  $f_n$  and replaces all values averaged with one average value. Segment averaging is an ensemble average at each value of  $f_n$  of a number of separate transforms.

These steps are the basis for two programs which will be used as examples. It should be noted that a real data sequence  $x_n$  will have a complex fourier transform  $X(f_n, N)$ . In a sense the real part is the coefficient of the cosine term and the imaginary part is the coefficient of the sine term. Therefore in step (4) when the power spectral density estimate is computed, the sum of the square of these two terms is used. In all examples and figures, the power spectral density has been normalized with the variance of the time series. This normalized power spectral density will be called  $F(f_n)$  or  $F(n)$ .

The smoothing in step (5) is one of the more subjective aspects of the procedure and the technique used will depend upon the type of signal being analyzed, the amount of computer time available, and the final use of the power spectral density. The smoothing and the choice of  $N$  and  $\Delta T$  will determine the frequency range of the smoothed power spectral density. There is some choice available in the determination of these parameters, and this choice should be made prior to taking the data.

The largest value of  $N$  which can be used in core with the CDC 6400 is  $8192 (2^{13})$ . This is the largest power of two which can be used for a data array and not exceed the available core. Frequencies will then run from 0 to  $(\frac{N}{2} - 1) * \frac{1}{T}$ . But  $T = N\Delta T$ , and therefore the frequencies will run from 0 to  $(\frac{N}{2} - 1) * \frac{1}{N\Delta T}$ . For large  $N$  this is approximately  $1/2\Delta T$ , the Nyquist frequency. The zero frequency value is generally not reliable because the record lengths are of a finite length. If the value were to be nearly exact, the total time of the input data record,  $T$ , should approach infinity. The increment between points is equal to  $\frac{1}{T}$  where  $T$  is the length in time of the input

data record. Recall  $T$  is equal to  $N\Delta T$ . Therefore the high frequency end of the power spectral density is determined by  $\Delta T$ , the time interval of the data record, and the low frequency end is determined by the length of the data record.

Normally the type signal to be examined will dictate the sample rate,  $1/\Delta T$ . Once this is determined, and if the maximum range possible is desired,  $N$  is 8192, the low frequency end of the power spectral density is also set. The following table gives these limits for sample rates available on the Systems-Development A-D system currently in use.

TABLE 1 - LIMITS FOR POWER SPECTRAL DENSITY COMPUTATION - SYSTEMS - DEVELOPMENT A-D SYSTEM. RECORD LENGTH = 8192.

$\Delta T$ (SEC)	SAMPLE RATE (1/SEC)	LOWER LIMIT (HZ)	UPPER LIMIT (HZ)
.004	250	.031	125.0
.002	500	.061	250.0
.001	1000	.122	500.0
.0005	2000	.244	1000.0
.00025	4000	.488	2000.0

If a smaller range is desired,  $N$  may be reduced and there will be a savings in computer costs. If a larger range is desired, a program is available which allows larger  $N$ 's to be used by employing an external storage device such as a disc. This program will be discussed later in this section.

Smoothing of the power spectral density is required. Two techniques are available: segment averaging and frequency averaging. These may be used independently or in a combined manner. In segment averaging, a number of power spectral densities are computed from separate records from the same signal. These estimates of the power spectral densities are treated as an ensemble, and an ensemble average computed. The number of segments used is determined by the quality of the smoothed power spectral density desired and the amount of computer time to be expended. Segment averaging will not alter the frequency range of the power spectral density, the upper limit will be  $1/2\Delta T$  and the lower limit  $1/T$ .

Frequency averaging involves averaging adjacent points of the power spectral density estimate from one data record. For example every  $m$  points could be averaged and replaced by one point at the midpoint of the frequency range of the original  $m$  points. This type of averaging will have a negligible effect on the high frequency limit of the power spectral density, but will normally raise the lower limit substantially, depending, of course, on the choice of  $m$  and the original  $\Delta T$ .

Factors which enter into the choice of frequency smoothing techniques are determined by the ultimate use of the power spectral density. If a well-smoothed plot is the desired output, a combination of frequency and segment averaging may be employed. If a correlation function is to be computed from the power spectral density function, then equal frequency spacing must be preserved. Also, the time spacing of the correlation obtained is determined by the frequency interval of the power spectral density and this relationship should be considered in any frequency smoothing.

#### 4.1 Calculation of Power Spectral Densities Using Segment Averaging Techniques

In order to provide some examples of the use of both the FFT and the averaging techniques, output from a specific program will be presented. This program, SEGEMNT, is listed in Appendix B2, and references will again be made to line numbers in the program.

This program follows the suggested routine for computation of a power spectral density. Lines 107-133 read one block of data 8192 elements long off of the data tape, tape 1, and compute the mean and the rms of that data record. Lines 138-151 remove the mean from the data and divide by the rms to obtain a rms of 1.0. This section of the program also tapers the data. Lines 156-167 perform a forward fourier transform of the array D, and segment average into array SEGMENT. Lines 171-194 reflect the segment averaged spectra and perform an inverse transform to obtain a correlation function. The remainder of the program is concerned with output and plots of both the correlation and the power spectral density. Frequency averaging is performed in lines 246-260.

Some sample results from this program will now be used to illustrate the effect of segment and frequency averaging. Segment averaging can be evaluated using both qualitative and quantitative methods. The appearance of both the smoothed spectra and the autocorrelation can be compared for different numbers of segments. Figure 6 shows four different segment averaged spectra computed from the same data record. All four of these spectra were also smoothed using frequency averaging over the high frequency portion. The portion of the title which is of the form xx-8192 indicates how many segments of length 8192 were used in the calculation of the spectra. It can be easily seen that as the total number of records increases, the spectra become smoother. If

the spectra are compared by laying one on another, there is no change in the best line that could be drawn through the data. In other words, if the 64-8192 case is compared with the 4-8192 case, the mean curves are identical. Additional qualitative comparisons can be made using a number of different criteria. The effective bandwidth, number of degrees of freedom and normalized standard error for the different cases can be computed using equations (9.140) to (9.149) of Bendat and Piersol (1). These values for the cases plotted in Figure 6 are shown in Table 2. As the number of segments averaged increases, the normalized standard error decreases. The effect of frequency averaging in reducing the normalized standard error can also be seen. Another means of comparison is available in terms of more physically relevant parameters. The area under the spectrum is compared in Table 3 for the four cases shown in Figure 6. There is very little difference in these integrated quantities as the number of segments increases. These values were all computed for the segment averaged spectra before frequency averaging. Close attention should be paid to the integral of  $F(n)$ . A value which is not very close to 1.00 is an indication that, for some reason, an incorrect spectrum has been obtained.

Figure 7 shows the qualitative effect of frequency averaging. All three cases were averaged over the same number of segments, and the differences are a result of frequency averaging alone. The last line of the titles indicate the type of frequency averaging used. The different averaging schemes are: (1) no frequency averaging (2) HF AVG 10 - no frequency averaging from 0-5.98 HZ, 10 points averaged

TABLE 2 - EFFECT OF SEGMENT AVERAGING ON POWER SPECTRAL DENSITY ESTIMATES

CASE	NUMBER OF POINTS FREQUENCY AVERAGED	RANGE OF SMOOTHING (HZ)	EFFECTIVE BANDWIDTH (HZ)	NUMBER OF DEGREES OF FREEDOM	NORMALIZED STANDARD ERROR
4-8192	1	0-5.98	.122	8	.500
	10	5.98-500.0	1.220	80	.158
8-8192	1	0-5.98	.122	16	.353
	10	5.98-500.0	1.220	160	.112
16-8192	1	0-5.98	.122	32	.250
	10	5.98-500.0	1.220	320	.079
64-8192	1	0-1.09	.122	128	.125
	3	1.09-5.98	.366	384	.072
	10	5.98-500.0	1.220	1280	.039

TABLE 3 - COMPARISON OF INTEGRATED PROPERTIES OF POWER SPECTRAL DENSITY ESTIMATES

CASE	$\int_0^{500} F(n) dn$
4-8192	1.014
8-8192	1.004
16-8192	1.002
64-8192	1.007

from 5.98-500 HZ (3) HF AVG 10 LF AVG 3 - no frequency averaging from 0-1.098 HZ, 3 points averaged from 1.098-5.98 HZ and 10 points averaged from 5.98-500 HZ. Table 4 is comparable to Table 2 and shows the effective bandwidths, number of degrees of freedom and normalized standard error for the cases shown in Figure 7. These criteria are the only ways to evaluate frequency averaging. In most cases frequency averaging will be used to provide a smooth plot of the spectra, and the means of frequency smoothing selected will be dependent upon the type of data being considered, the frequency range of interest, and the ultimate use of the plot.

TABLE 4 - EFFECT OF FREQUENCY AVERAGING ON POWER SPECTRAL DENSITY ESTIMATES

CASE	NUMBER OF POINTS FREQUENCY AVERAGED	RANGE OF SMOOTHING (HZ)	EFFECTIVE BANDWIDTH (HZ)	NUMBER OF DEGREES OF FREEDOM	NORMALIZED STANDARD ERROR
4-8192	1	0-500.0	.122	8	.500
4-8192	1	0-5.98	.122	8	.500
	10	5.98-500.0	1.220	80	.158
4-8192	1	0-1.09	.122	8	.500
	3	1.09-5.98	.366	24	.289
	10	5.98-500.0	1.220	80	.158

Some additional guidelines which may be used in the selection of how many segments to average may be obtained from considerations of the autocorrelation function obtained from the segment averaged spectra.

In order to compute an inverse fourier transform, the smoothed spectra must consist of equally spaced frequency increments. Generally the spectra to be used will only be segment averaged and not frequency

averaged in order to preserve equal frequency spacing. In all of the cases which will be discussed, the segment averaged spectra was transformed using the techniques outlined in section 3. Figure 8 is a plot of the autocorrelation functions obtained from the spectra shown in Figure 6. In all cases the plots are quite similar up to a lag time of .2 seconds. For longer lag times there is more difference evident. As the number of segments used in the frequency averaging increases, the value of the autocorrelation stays closer to zero for lag times from .2 to 1.0 seconds. Table 5 shows the areas of the autocorrelation function up to the first zero crossing and also from 0 to 4.096 seconds. There is up to a 25 percent difference in the area to the first zero crossing between the different cases although the spectra of Figure 6 appear to be virtually identical. The areas computed over the full range of the autocorrelation are at least one order of magnitude less than the areas to the first zero crossing. A more detailed discussion of the reason for the difference in the areas is presented in the following paragraphs. These two problems represent a significant difficulty if one is interested in computing an integral scale.

TABLE 5 - EFFECT OF SEGMENT AVERAGING ON THE AREA UNDER THE AUTOCORRELATION FUNCTION

CASE	AREA TO FIRST ZERO CROSSING	AREA 0-4.096 SECONDS
4-8192	.0405	.00142
8-8192	.0363	.00157
16-8192	.0336	.00195
64-8192	.0280	.00187

In order to try to get a more accurate calculation of the autocorrelation function, a program was written to calculate the autocorrelation directly from the data record. This is a much more expensive method than the FFT technique and not as many cases were run. A comparison of the autocorrelations obtained using a direct calculation and using an inverse fourier transform of a spectra is shown in Figure 9. The plots with the title PROGRAM ACR were computed directly using a data record of the indicated length in 8 second segments. For a 32 second record, 4 separate autocorrelations were computed and averaged in a manner analogous to segment averaging of the spectra. The cost of calculation was such that in the direct case, the computation was only carried out to a lag time of .9 seconds. Therefore, the only direct comparison which can be made between the plots is the area up to the first zero crossing. For the 32 second record, the area to the first zero crossing is .0333 for the direct calculation and .0405 for the FFT calculation. For the 64 second record, the area is .0362 for the direct calculation and .0363 for the FFT calculation. It is interesting to note the comparison in cost to obtain an autocorrelation via the direct method with that for the FFT technique. For the lower two plots of Figure 10, both of which represent a data record of approximately 64 seconds of real time, the direct calculation for 100 values of time lag cost \$28.00 while the FFT calculation costs \$5.40 for 4096 values of time lag. This is a factor of 5 differences in cost for 40 times fewer correlation points. The FFT technique also provides a spectrum for the cost indicated.

( In the course of the direct calculation of the autocorrelation function, an interesting effect of the length of the record used in the

calculation was observed. The direct calculation was initially carried out using a record length of 2000 (2 seconds) and the maximum lag computed corresponded to 1000 data values (1 second). Two examples of this calculation are shown in Figure 10. In both cases where records of 2 seconds each were used, the autocorrelation is negative from a time lag of 0.3 seconds to a time lag of 1.0 seconds. This was not the case in any of the computations which used the FFT. In order to see what effect record length had on this negative region, the direct calculation program was modified to use a record length of 8000 (8 seconds). The results of these computations for the same total length of data are also shown in Figure 10. The negative region from .3 to 1.0 is no longer predominant, and these results agree well with the autocorrelations obtained from the FFT routines as shown in Figure 9.

An explanation for this difference can be made based on physical arguments. A time lag of .5 seconds corresponds to a frequency of 2HZ. In a 2 second record there would only be 4 cycles at this frequency and fewer cycles at any lower frequency (longer time lags). It seems that 4 cycles are not enough to adequately average in the calculation of an autocorrelation. By using a record length of 8 seconds, there will be 16 cycles of a 2HZ signal in one record, and the resolution at lag times of .5 seconds will be better. Based on a limited amount of experience with this particular record, it is felt that at least 8 cycles of a particular frequency should be present to obtain adequate resolution in an autocorrelation function at a lag time corresponding to the reciprocal of the frequency.

An additional effect of interest also arose in one case. A digital data tape was used which had more than one channel of data.

For a small portion of one record, the channels were reversed and the effect on the power spectral density is shown in Figure 11. The noise in the high frequency portion of the spectra is due to the channel switch. The second plot is of the same data but avoiding the record with the channel switch.

The cost of the various cases run with program SEGEMNT are listed in Table 6. These include the computation of a power spectral density, an autocorrelation and plots of both using the U200 plotting routines available at the Engineering Research Center, Colorado State University.

TABLE 6 - COST FOR TEST CASES - PROGRAM SEGEMNT  
CENTRAL PROCESSOR COST = \$290/hr

NUMBER OF SEGMENTS OF LENGTH 8192	TIME OF TOTAL AMOUNT OF DATA (SECONDS)	COST \$
4	32.77	4.00
8	65.54	5.40
16	131.07	8.92
64	524.29	27.82

It is important to bear in mind that all of the examples in this section have been calculated using a record of pressure data obtained using a linear transducer. Non-linear transducers or signals of a different type which require different frequency range or which were taken at a different sample rate would alter the cost figures. As such, these examples should only be considered as guidelines in selecting a scheme for digital analysis.

#### 4.2 Calculation of Power Spectral Densities Using an External Core FFT Algorithm

In some applications, it is desirable to have a greater frequency range of the power spectral density, or resolution of the autocorrelation at relatively large lag times. In order to obtain either of these results, a long record of data must be used for each segment. In order to stay within the present available core of the CDC 6400,  $(140000_8)$ , the longest data record which is a power of two which may be used is 8192. A technique is available which allows longer data records to be considered by making use of disc storage and performing the FFT in pieces. The details of the algorithm are described by Brenner (3). A program titled FOR2D is available from the IBM Contributed Program Library (#360D-13.4006). This program was written by Norman Brenner and uses the algorithm of reference 3. The program allows record lengths limited only by the disc storage available on the computer system in use (presently between 2,000,000 and 3,000,000 for the CSU CDC 6400 system). This capability allows very long record lengths to be used if necessary. The cost of the calculations becomes large as longer records are used and in many cases becomes a limiting factor. A comparison of external core techniques and segment averaging techniques is discussed in section 4.3.

In order to use an external core type of program, the input data record is broken into a series of equal length records. It is necessary to be able to store 3 of these records in the core of the computer at any given time. This requirement will set the length of this array. The input data record is then stored on the disc and the FFT routine only calls a portion of the record at a time. It is important to

understand that this is not a segment averaged technique, but that the resulting sequence of points is the same that would be obtained if the entire data record were transformed using a computer with a very large core.

A listing of a program written to utilize the external core technique, EXTCORE is in Appendix B3. A listing of subroutine FOR2D is in Appendix A2.

The steps necessary to calculate a power spectral density are basically the same as were listed in section 4.1. The only differences between program EXTCORE and SEGEMNT are in the input and averaging. These differences will be pointed out with reference to line numbers in Appendix B3.

In lines 145-170, the data is read from the data tape (tape 1) in units compatible with the length of the records to be stored in mass storage. These records are available to the program by calling subroutine DREAD. Lines 187-205 remove the mean from the data and taper the data. FOR2D is called in line 209. The remainder of the program involves frequency averaging, output, and plotting.

The frequency averaging is similar to that described in the previous section except that even the low frequency portion of the spectrum is frequency averaged. Since only one segment is run, some frequency averaging is necessary even in the low frequency portions in order to obtain acceptable levels of statistical reliability.

The power spectral densities obtained from four different cases using program EXTCORE are shown in Figure 12. The notation in the figures indicates how many portions were used to make up the entire record. The figure in the bottom right utilized a record made up of

512 parts, each consisting of 1024 data elements. The averaging in the three shorter cases was such that the bandwidths for all three were the same. The fourth case (512-1024) used a different scheme of frequency averaging. The details of the frequency averaging along with the number of degrees of freedom, and the normalized standard error are shown in Table 7. This table can be compared with Tables 2 and 4 of section 4.1. It can be easily seen that as the normalized standard error decreases, the power spectral density function becomes smoother.

TABLE 7 - EFFECT OF RECORD LENGTH ON POWER SPECTRAL DENSITY ESTIMATES, EXTERNAL CORE FFT

CASE	NUMBER OF POINTS FREQUENCY AVERAGED	RANGE OF SMOOTHING (HZ)	EFFECTIVE BANDWIDTH (HZ)	NUMBER OF DEGREES OF FREEDOM	NORMALIZED STANDARD ERROR
32-1024	8	0-31.25	.244	16	.353
(32.77 SEC)	16	31.25-62.50	.488	32	.250
	128	62.50-500.0	3.906	256	.088
64-1024	16	0-15.63	.244	32	.250
(65.54 SEC)	32	15.63-31.25	.488	64	.177
	256	31.25-500.0	3.906	512	.063
128-1024	32	0-7.81	.244	64	.177
(131.07 SEC)	64	7.81-15.63	.488	128	.125
	512	15.63-500.0	3.906	1024	.044
512-1024	16	0-1.95	.030	32	.250
(524.29 SEC)	64	1.95-21.48	.122	128	.125
	256	21.48-41.02	.488	512	.063
	512	41.02-500.0	.977	1024	.044

Table 8 shows the values of the areas under the spectra of Figure 12. This table is comparable to Table 3 of section 4.1. The first case (32-1024) shows more variation than any of the other cases in Table 3 or Table 8, but for many applications this error would be acceptable.

TABLE 8 - COMPARISON OF INTEGRATED PROPERTIES OF POWER SPECTRAL DENSITY ESTIMATES, EXTERNAL CORE FFT

CASE	$\int_0^{\infty} F(n) dn$
32-1024	.978
64-1024	1.016
128-124	1.009
512-1024	.997

Correlation functions were computed for three of the example cases and are shown in Figure 13 along with one case calculated with program SEGEMNT. A trend can be seen in these figures which is similar to that of Figure 8. As the length of record increases, the correlation at larger lag times is more nearly zero. The correlations computed using program EXTCORE all have very much larger record lengths than those computed using program SEGEMNT. It would be expected that the EXTCORE correlations would be valid for longer lag times. A listing of the areas for the three correlations computed is shown in Table 9. In all of the cases, the area to the first zero crossing is comparable to that for the entire autocorrelation (0-4.096 sec). This agreement is in contrast with the cases shown in Table 5 for the shorter records of

program SEGEMNT. This is another example of the effect of record length on the calculation of autocorrelation functions. There is fair agreement between the areas out to the first zero crossing in both cases, and this may be an appropriate choice of area when only a limited record length is available. Care must be used in using the area to the first zero crossing, since not all correlations remain as close to zero as this demonstration case for regions beyond the first zero crossing.

TABLE 9 - EFFECT OF RECORD LENGTH ON THE AREA UNDER THE AUTOCORRELATION FUNCTION, EXTERNAL CORE FFT

CASE	RECORD LENGTH SECONDS	AREA TO FIRST ZERO CROSSING	AREA 0-4.096 SEC
32-1024	32.77	.0362	.0339
64-1024	65.54	.0378	.0376
128-1024	131.07	.0333	.0350

The costs for the EXTCORE examples are listed in Table 10. These include the cost of all calculations and plotting.

TABLE 10 - COST FOR TEST CASES PROGRAM EXTCORE.  
CENTRAL PROCESSOR COST = \$290/hr

CASE	DATA LENGTH SECONDS	COST \$
32-1024	32.77	12.10
64-1024	65.54	22.59
128-1024	131.07	46.37
512-1024	524.29	210.30

#### 4.3 Comparison of Program SEGEMNT and Program EXTCORE

Many of the differences between and advantages of segment averaging and external core approaches are apparent after reading the previous section. These differences and advantages will be briefly summarized in order to point out the most significant.

The major advantages of the external core technique are that it allows a greater frequency range in the spectrum and provides an autocorrelation function which is valid at relatively long lag times. The advantage of being able to obtain more points at low frequency in the spectrum is offset somewhat by the need to perform some type of smoothing in order to obtain a statistically reliable value. For the external core case, the smoothing will be accomplished using frequency averaging which will reduce the number of data points available at the low frequency end of the spectrum.

The autocorrelation which may be obtained using the external core technique is of higher quality at higher lag times than the autocorrelation which may be obtained using segment averaging. This increase in quality is obtained at a corresponding increase in cost of computer time. This extra cost may be necessary if an accurate measure of integral scale is desired. The integral time scale and the low frequency end of the power spectral density are directly related, ( $F(0) = 4 \int_0^\infty R(t)dt$ ), and if the low frequency end of the spectra has a standard error of .5, there can be up to 50 percent error in the integral scale.

The major advantage of segment averaging is cost. In all cases, comparable quality power spectral densities can be obtained (based on

normalized standard error) for from 1/3 to 1/8 the cost using segment averaging instead of external core techniques.

The core requirements for each case are comparable based on the array sizes used in the example programs. Changing array sizes in either of the programs would have an effect on the core required, but a comparable change would have to be made to both programs and the core requirements would still be comparable.

A general guideline in selecting a technique would be to use segment averaging unless a special requirement exists which requires the external core technique.

##### 5. TWO CHANNEL CALCULATIONS--CROSS-SPECTRAL DENSITIES AND CROSS-CORRELATIONS

Some applications require information concerning the relationship between two time series in either the frequency or time domains. Once the techniques described in the previous sections are understood, the computation of functions describing these relationships can be readily accomplished. Most computations of multichannel functions begin with a cross-spectral density function, a complex quantity. Once the cross-spectral density function is obtained, a number of additional quantities can be computed. A brief discussion of some of these functions can be found in Bendat and Piersol (1), pp. 25-34.

The equation for the cross-spectral density of two time series  $x(t)$  and  $y(t)$  is given by the equation  $G_{xy}(f_n) = \frac{2}{T} X^*(f_n) Y(f_n)$ . ( $X^*$  is the complex conjugate of the transform of the  $x(t)$  time series.) Thus, once the transforms of two simultaneous time series are available, the cross spectral density, and any other related quantities may be computed. As brief examples of both computation and averaging

techniques, programs which compute a coherence function and a cross-correlation coefficient will be discussed.

The two most important aspects of these programs are the techniques of data storage and averaging. The data storage is common to both programs and will be explained with reference to PROGRAM CSPECT2 (Appendix B4). The single channel transforms have been computed and are stored on a master data tape (tape 2) as separate files, with each segment a separate record (logical record) of the file. The input portion of the program (lines 90-105) reads each file from tape 2 and stores them on tape 3 and tape 4 for  $X(f_n)$  and  $Y(f_n)$  respectively. All reads and writes are done using unformatted binary reads and writes. The use of this type statement instead of a formatted read or write results in savings of from 50 percent to 90 percent in the required computer central processor costs.

As shown in previous sections, some method of averaging will be required to obtain statistically reliable estimates. In the examples segment averaging is used as the primary method. It is necessary to segment average the cross-spectral density function and not the single channel transforms. Therefore, in lines 110 and 111 the single channel transform for each segment is read and the segment averaged cross-spectral density function is computed. In the calculation of the coherence function (lines 113-130) the cross-spectral density is also frequency averaged prior to the final calculation of the coherence function (lines 138-156).

A second example program which calculates a cross-correlation function (PROGRAM CSPECT3) is listed in Appendix B5. The input and smoothing sections of this program are the same as those in CSPECT2.

The cross-correlation is obtained from an inverse fourier transform of the cross-spectral density function. A segment averaged cross-spectral density is computed in lines 106-113 and reflected in lines 117-122. The cross-spectral density is reflected such that the real part is an even function and the imaginary part an odd function. The reflected cross-spectral density is transformed in line 126 to obtain a cross-correlation coefficient. The cross-correlation coefficient can be calculated directly from the time series, and a comparison of a direct computation and a FFT computation is shown in Figure 14. The two results are virtually identical.

This brief section shows just two of the many cross-channel computations possible. Costs of the different calculations will vary with the application and no definite guidelines can be stated. The two most important aspects of cross-channel calculations are (1) use of binary write and read statements (2) averaging the cross-spectrum and not the single channel transforms.

## REFERENCES

1. Bendat, J. S., and Piersol, A. G., Random Data: Analysis and Measurement Procedures, Wiley-Interscience, New York, 1971.
2. Enochson, Soren D., and Ontes, Robert K., Programming and Analysis for Digital Time Series Data, The Shock and Vibration Information Center, United States Department of Defense, 1968.
3. Brenner, Norman M., "Fast Fourier Transform of Externally Stored Data," IEEE Transactions on Audio and Electroacoustics, Vol. AU17-No. 2, June 1969.

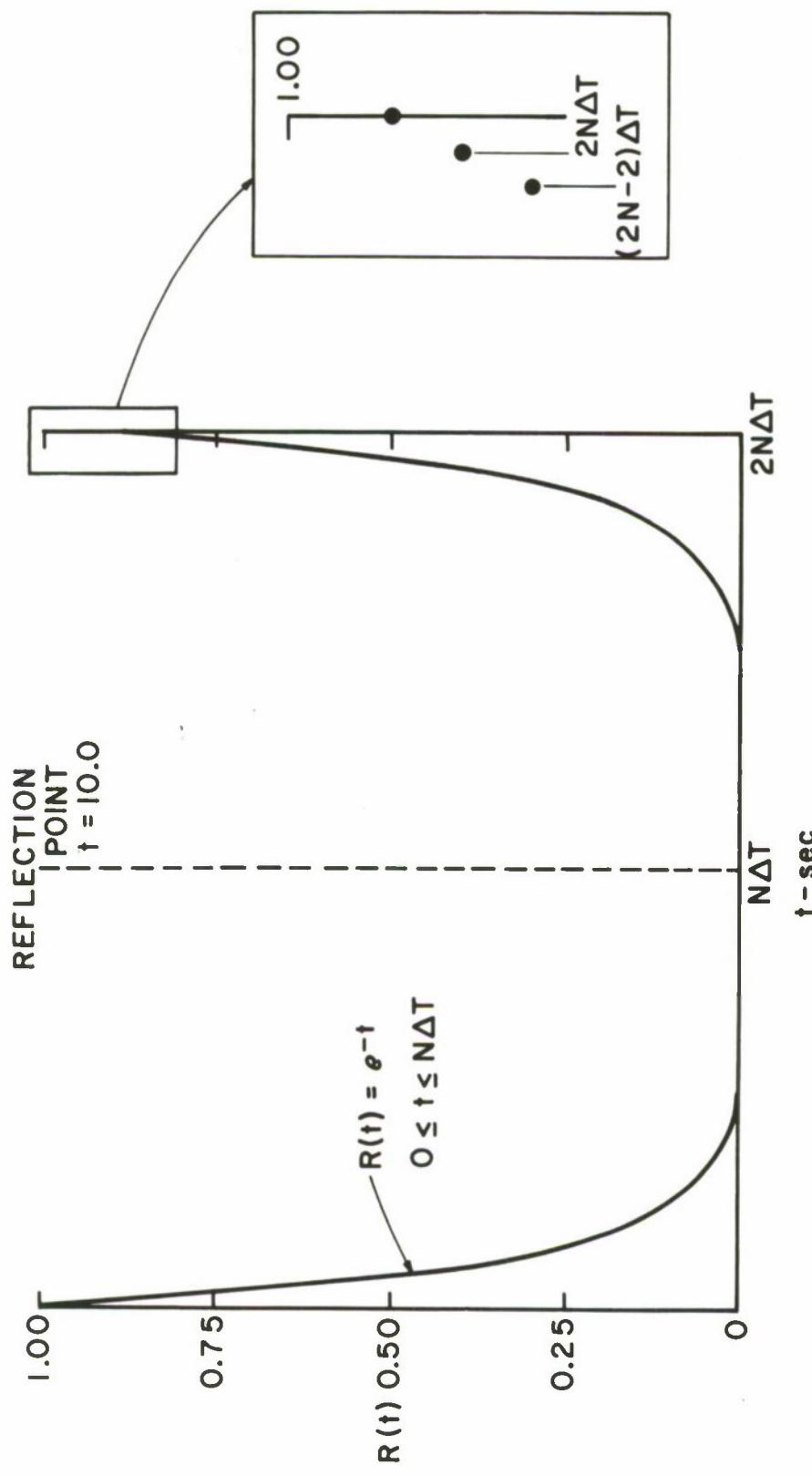


FIGURE 1. REFLECTION OF AUTOCORRELATION.

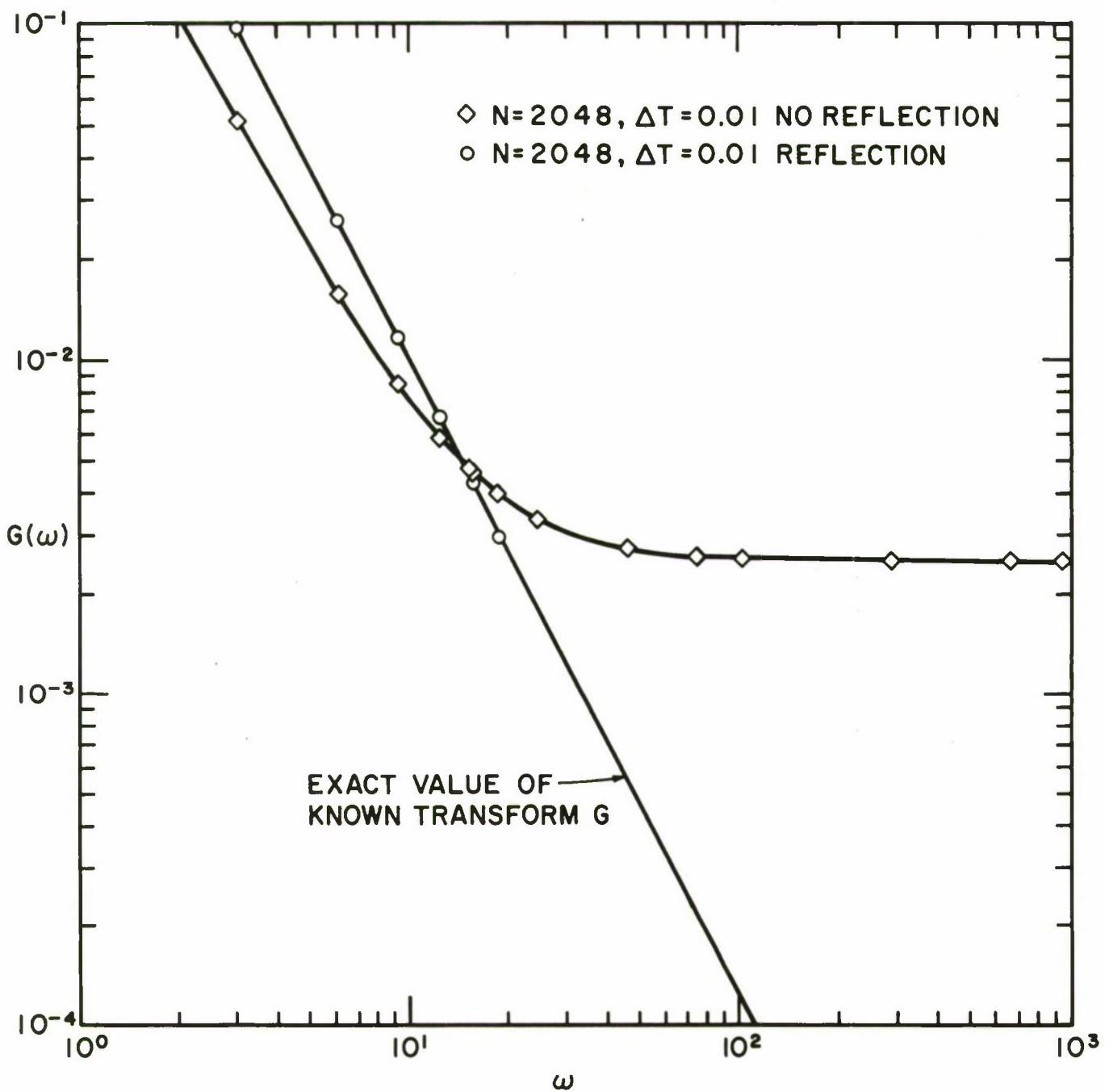
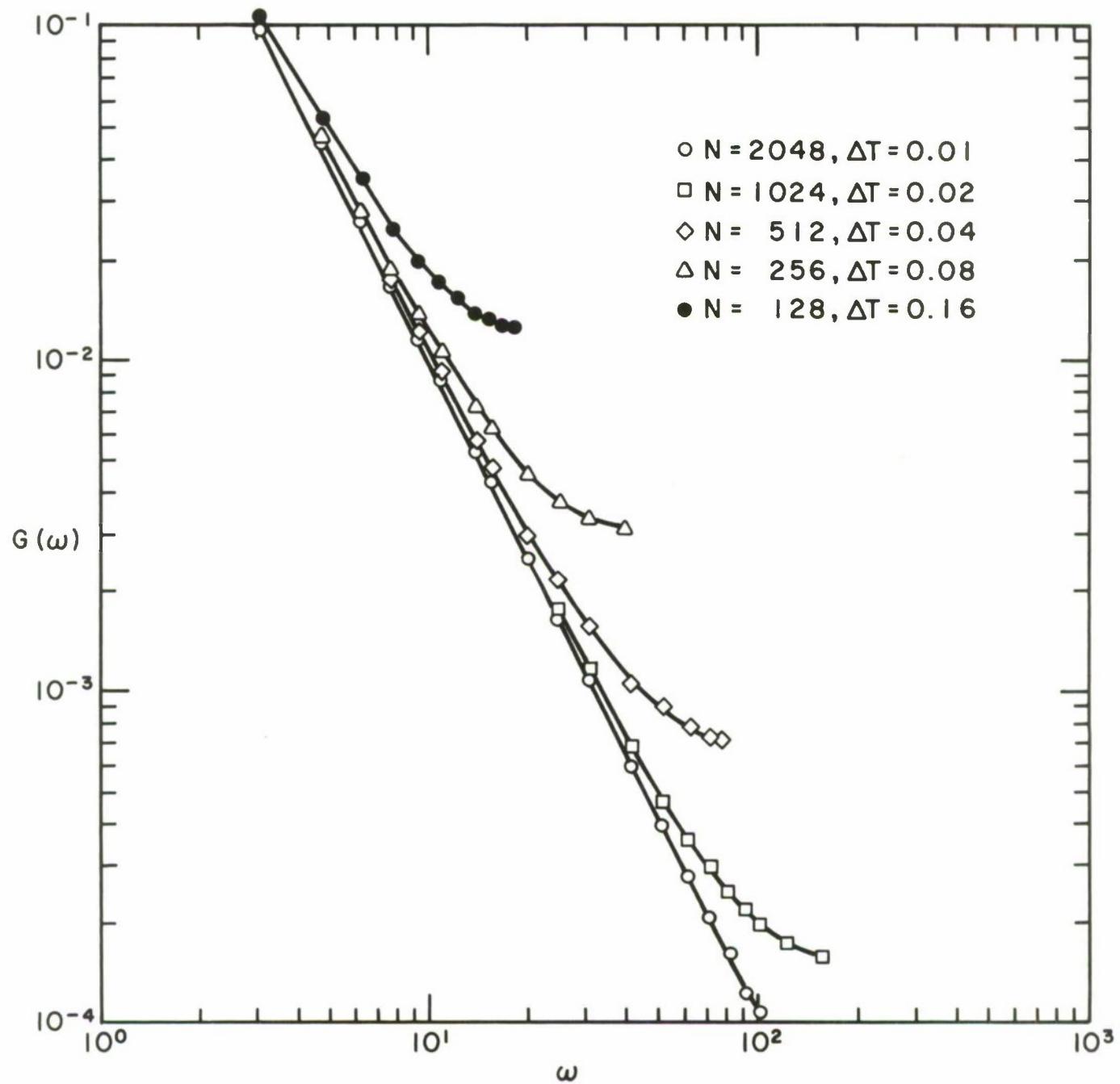


FIGURE 2. EFFECT OF TRANSFORMING  $R(t)$  PRIOR TO TRANSFORMING.

FIGURE 3. COMPARISON OF  $G(\omega)$ .

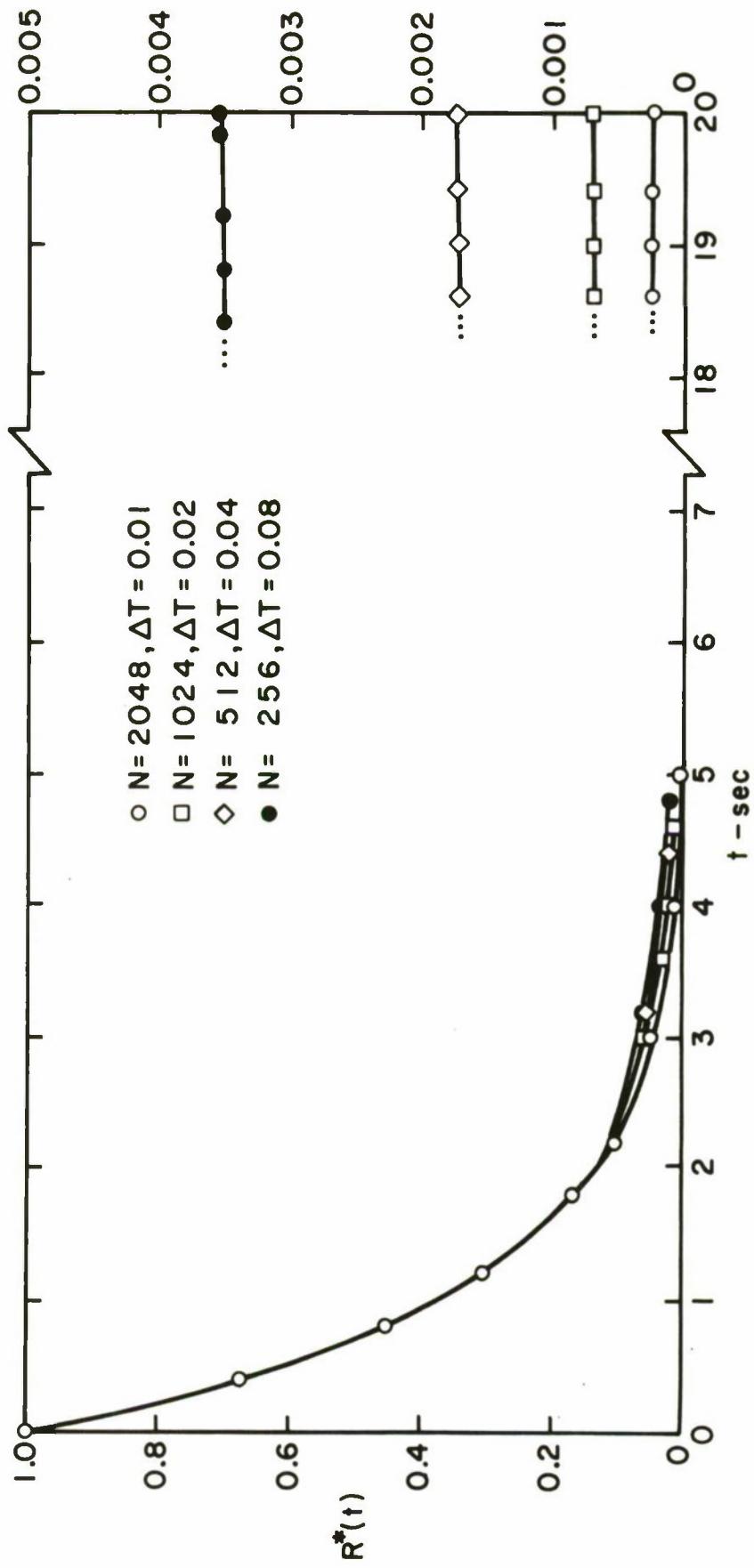


FIGURE 4. COMPARISON OF  $R^*(t)$ .

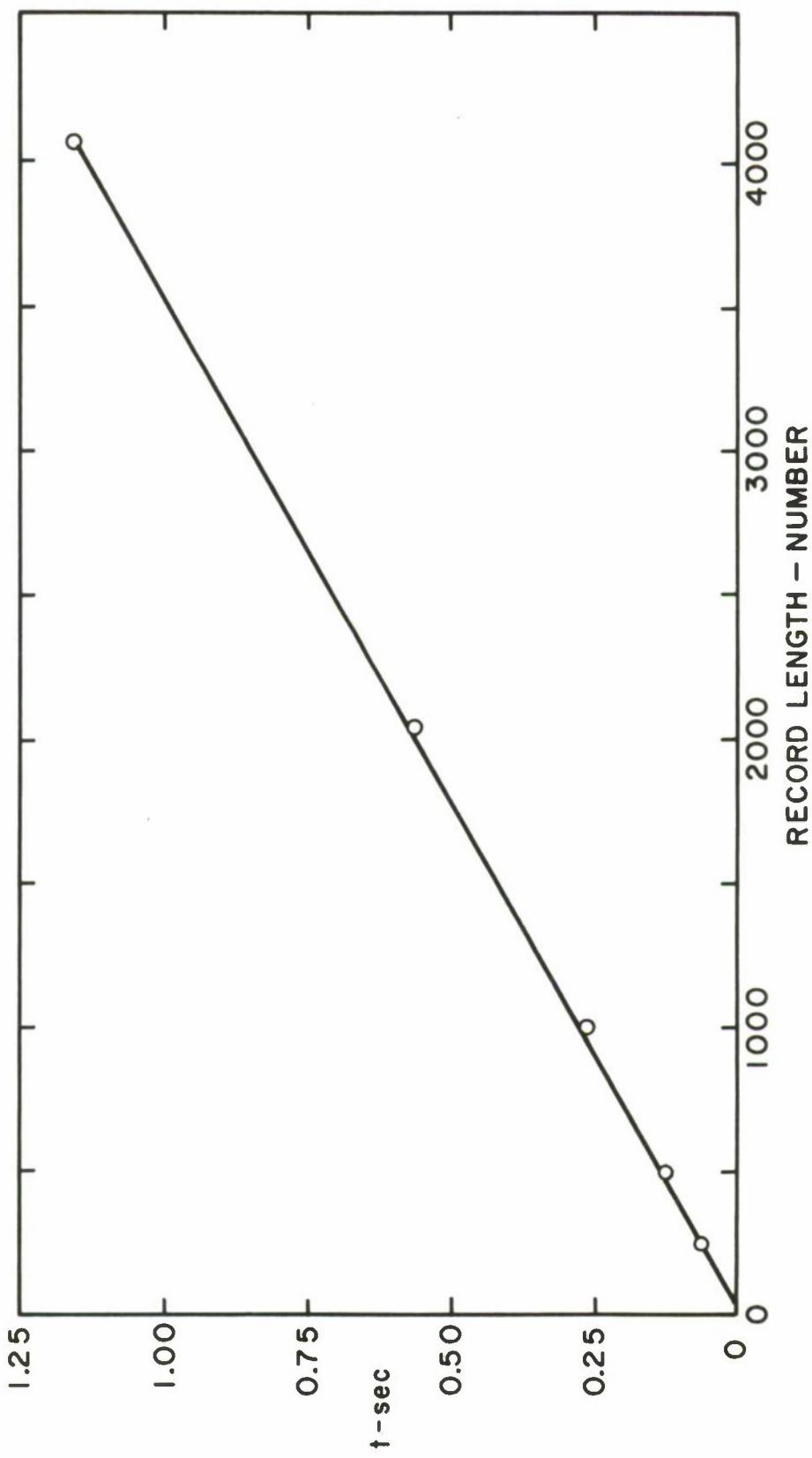


FIGURE 5. EXECUTION TIME--PROGRAM FOURT.

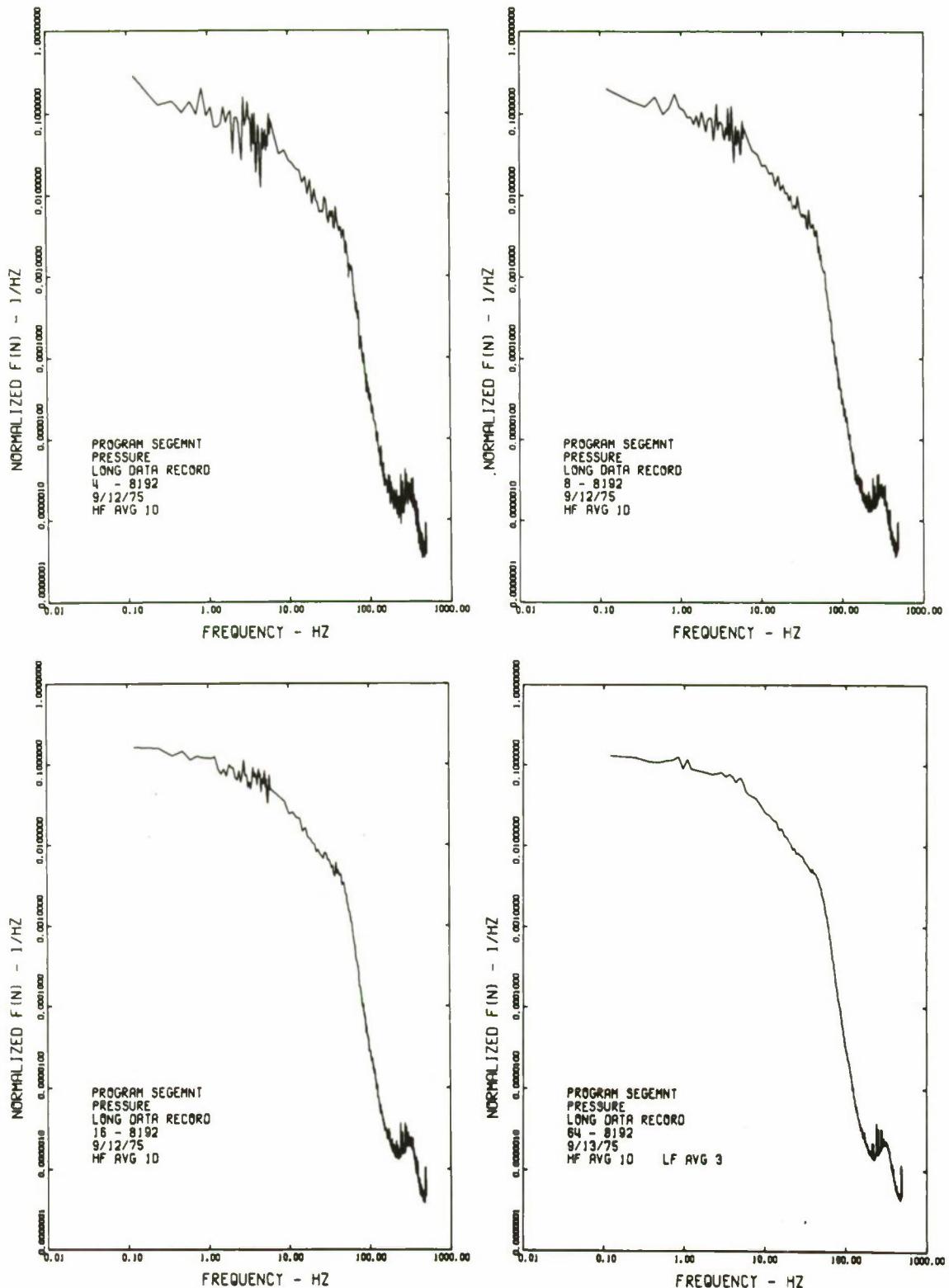


FIGURE 6. SEGMENT AVERAGED POWER SPECTRAL DENSITIES--  
PROGRAM SEGEMNT.

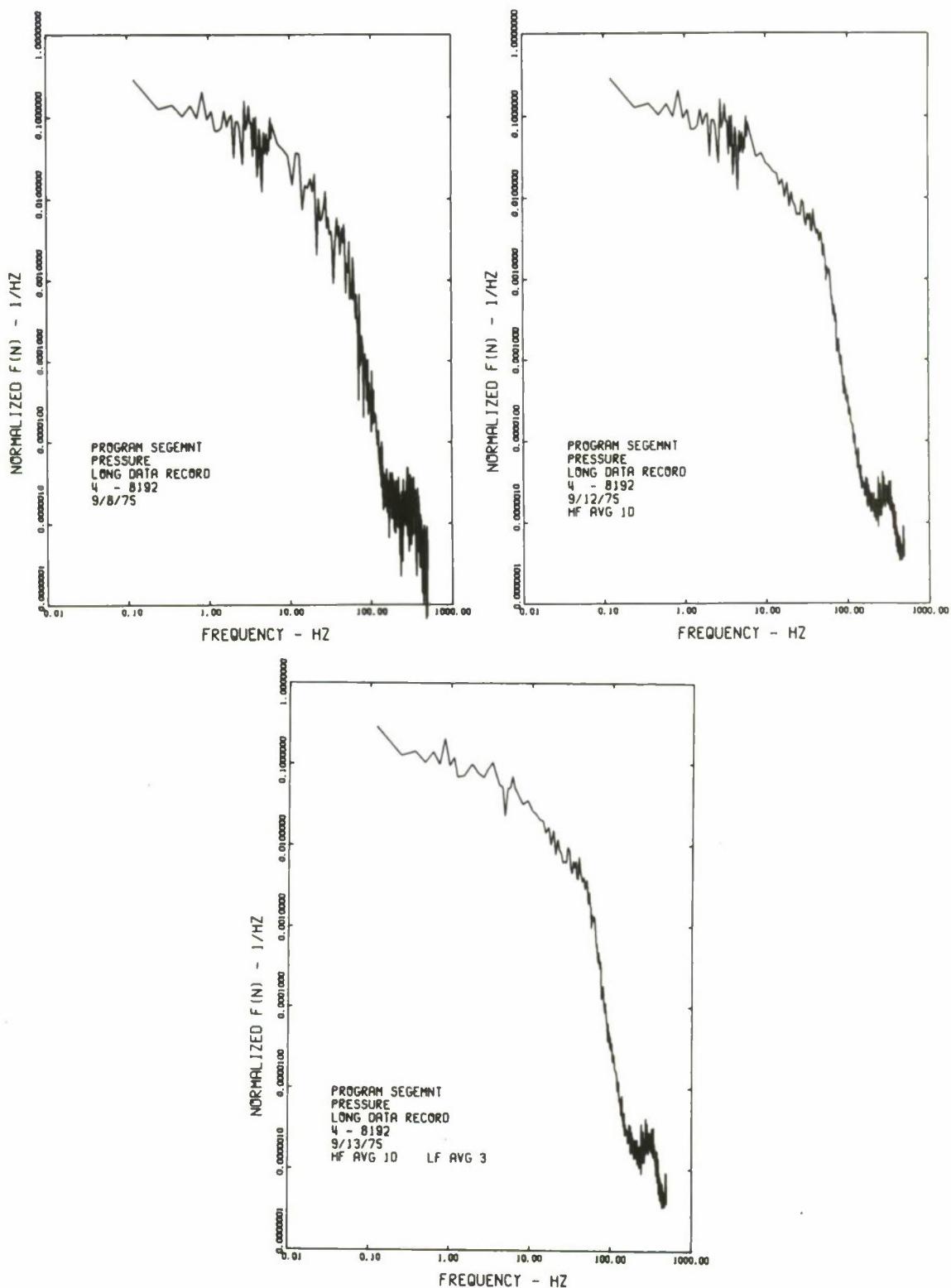


FIGURE 7. FREQUENCY AVERAGED POWER SPECTRAL DENSITIES--  
PROGRAM SEGEMNT.

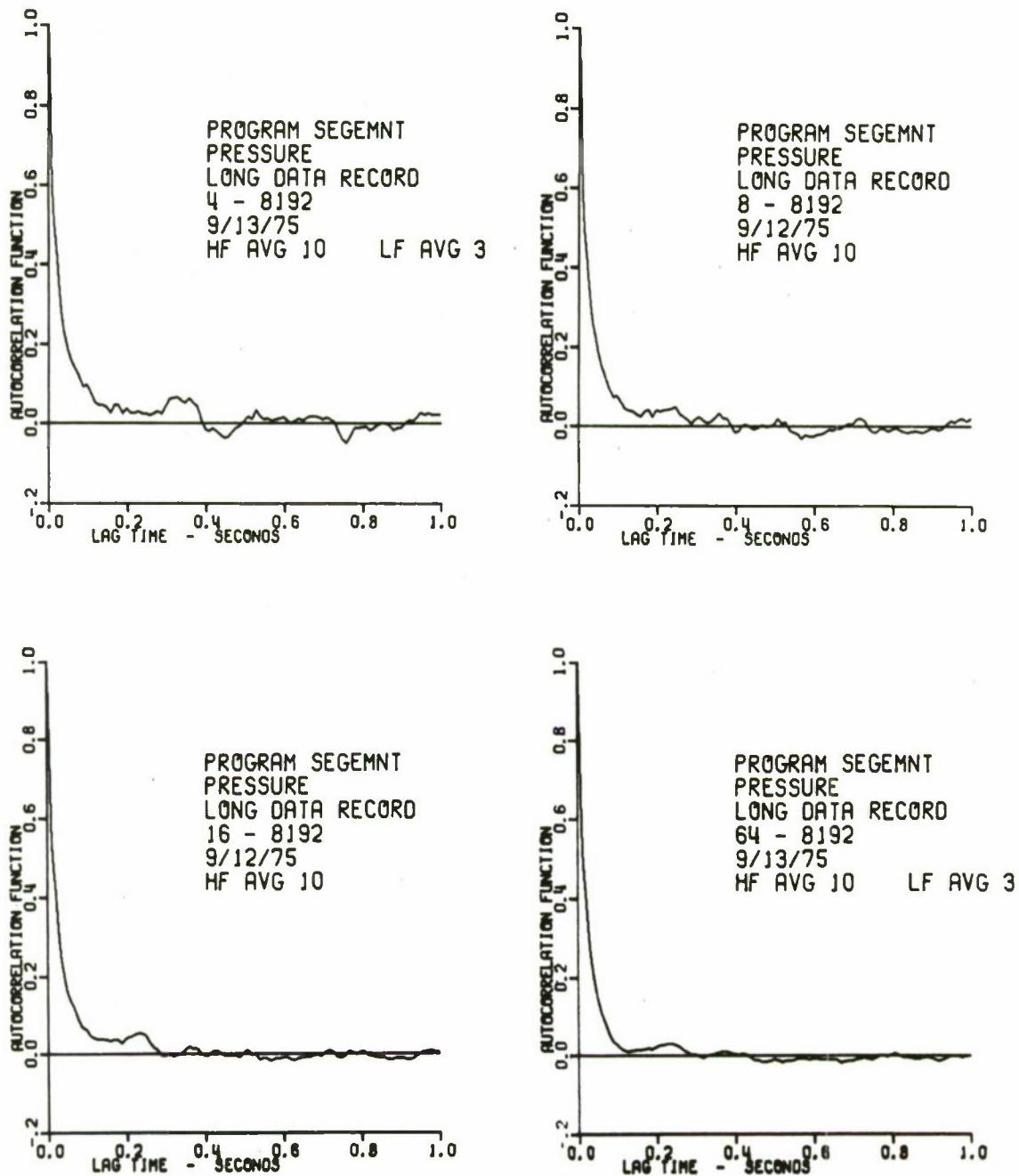


FIGURE 8. AUTOCORRELATIONS--PROGRAM SEGEMNT.

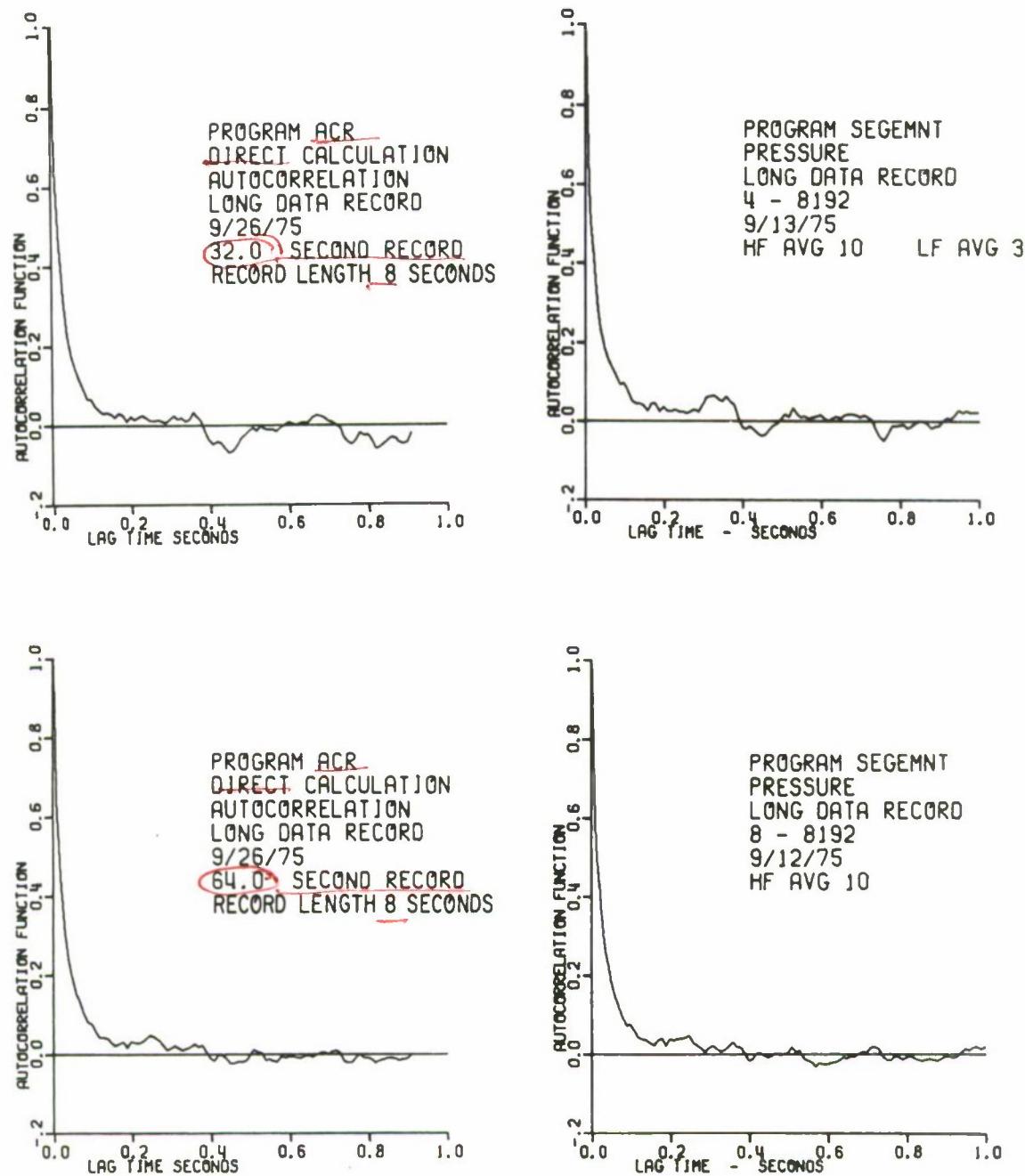


FIGURE 9. COMPARISON OF AUTOCORRELATIONS--PROGRAM SEGEMNT AND DIRECT CALCULATION.

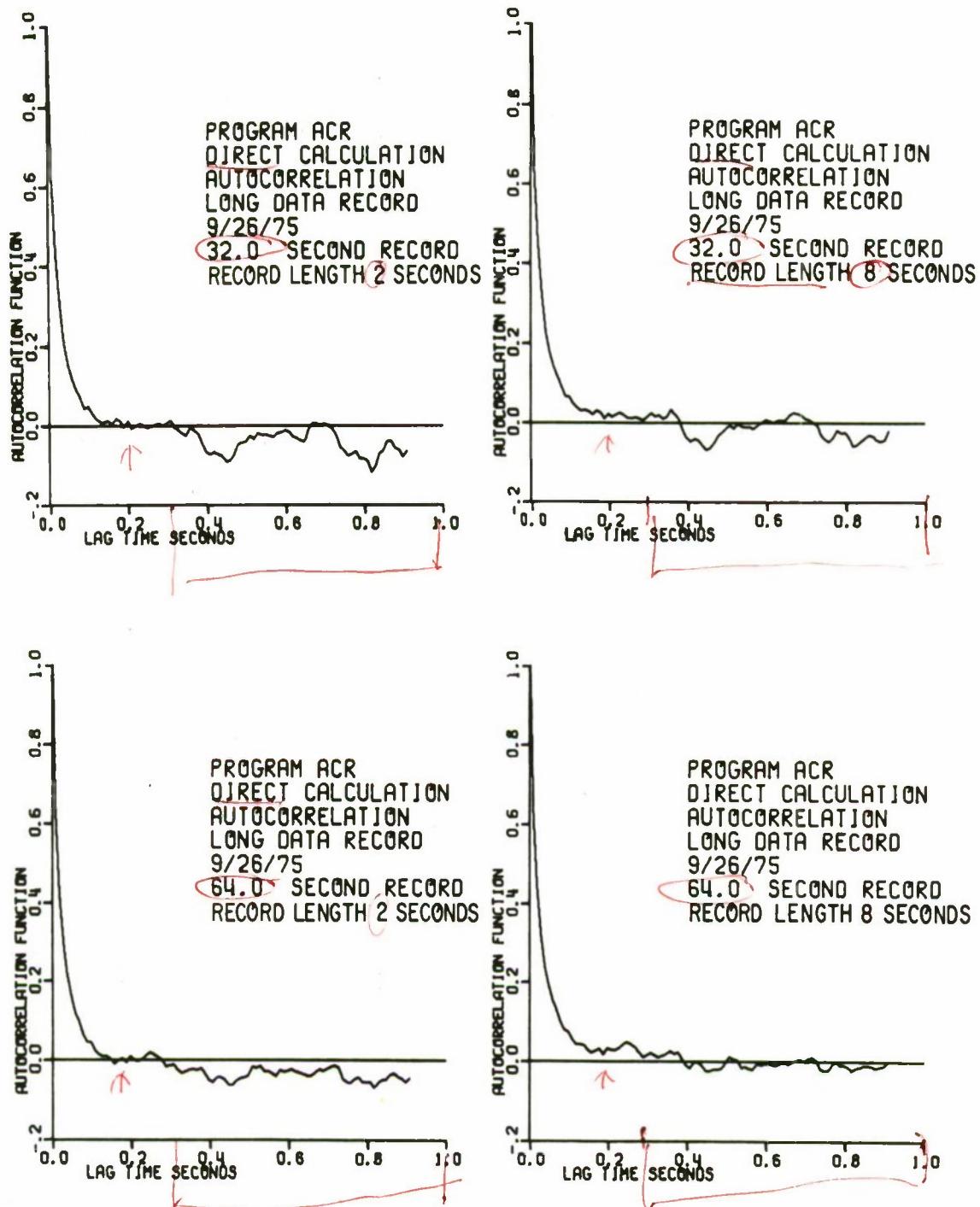


FIGURE 10. EFFECT OF RECORD LENGTH ON DIRECT CALCULATION OF AUTOCORRELATION.

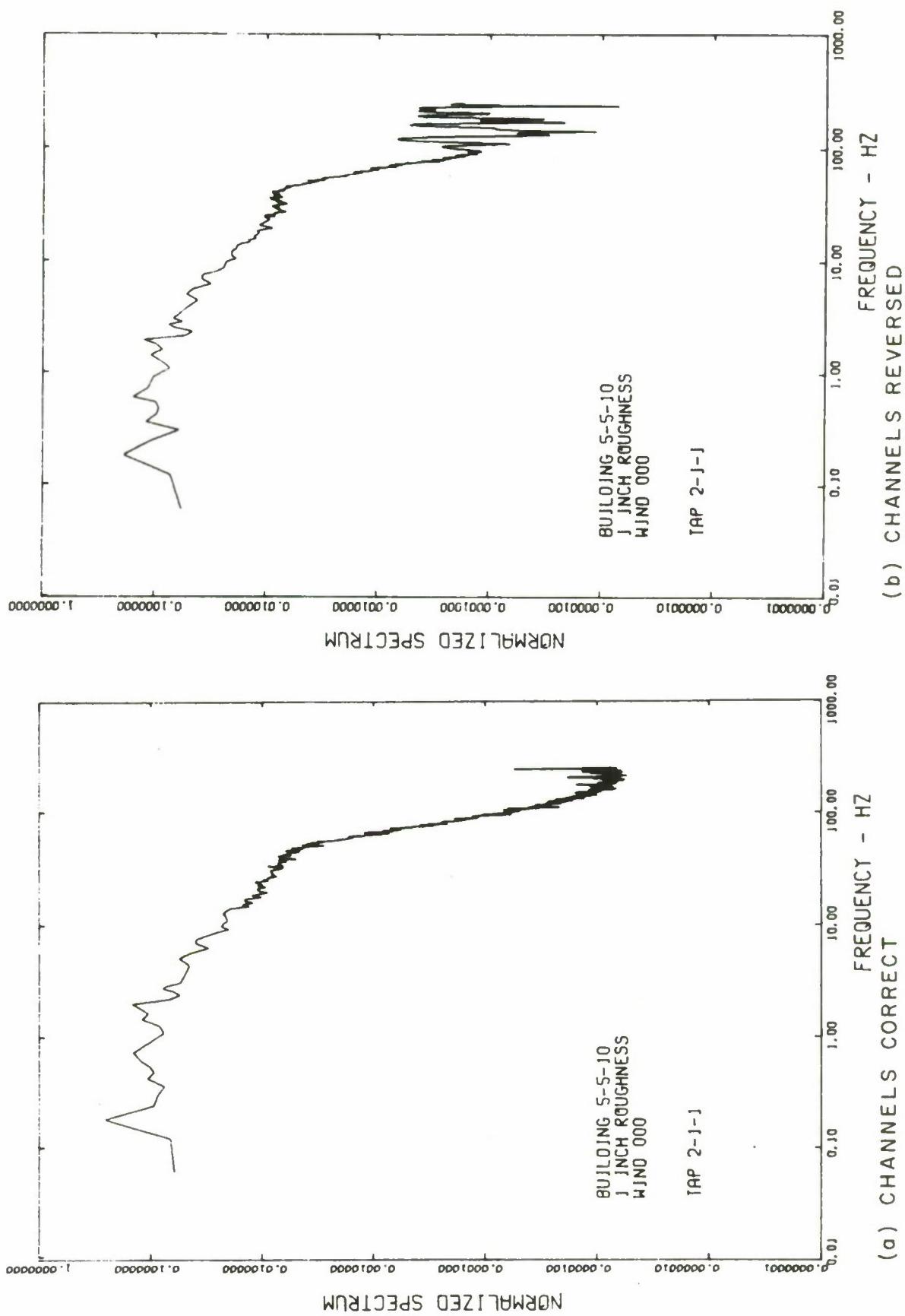


FIGURE 11. EFFECT OF REVERSED CHANNELS.

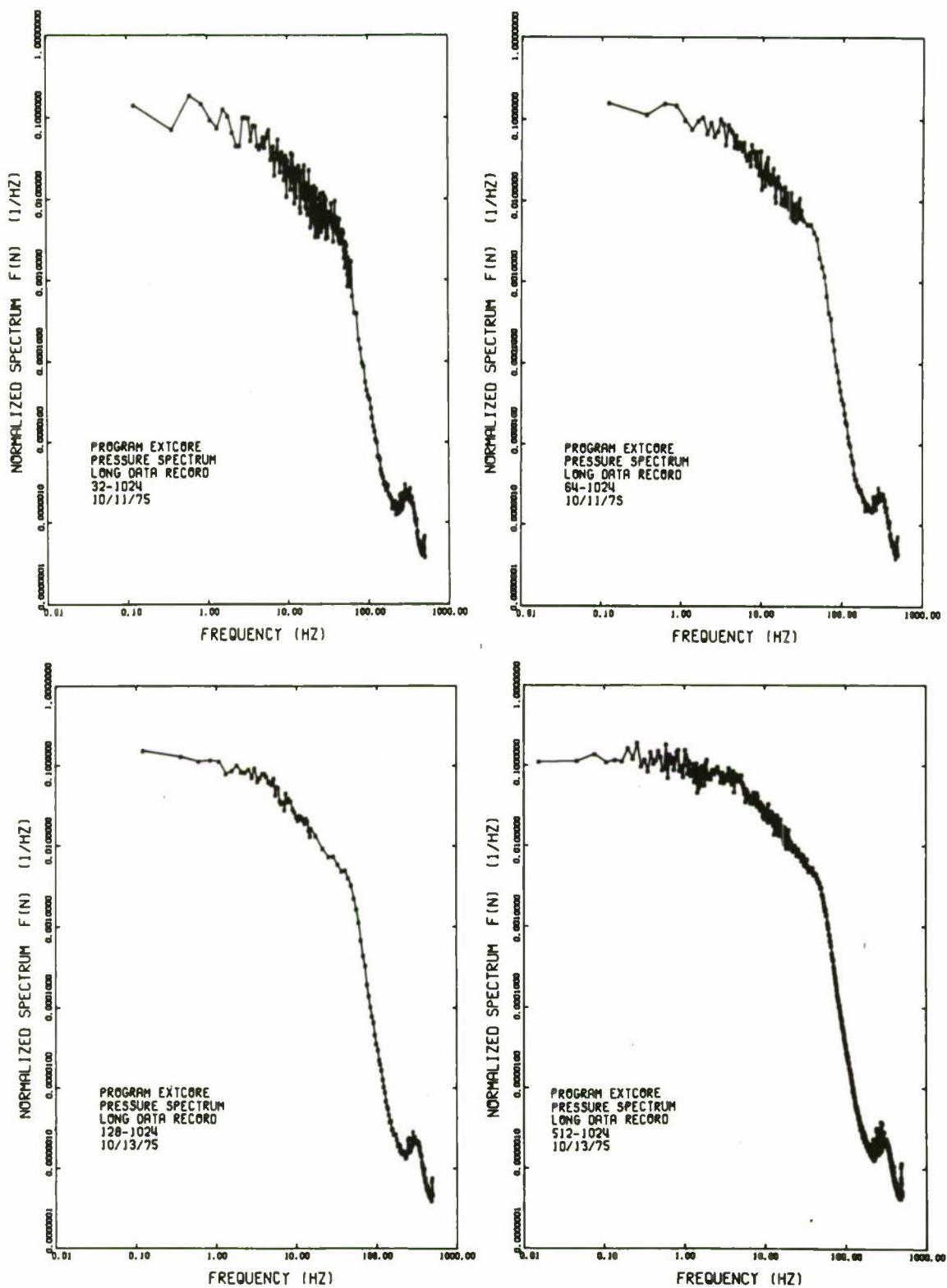


FIGURE 12. POWER SPECTRAL DENSITIES--PROGRAM EXTCORE.

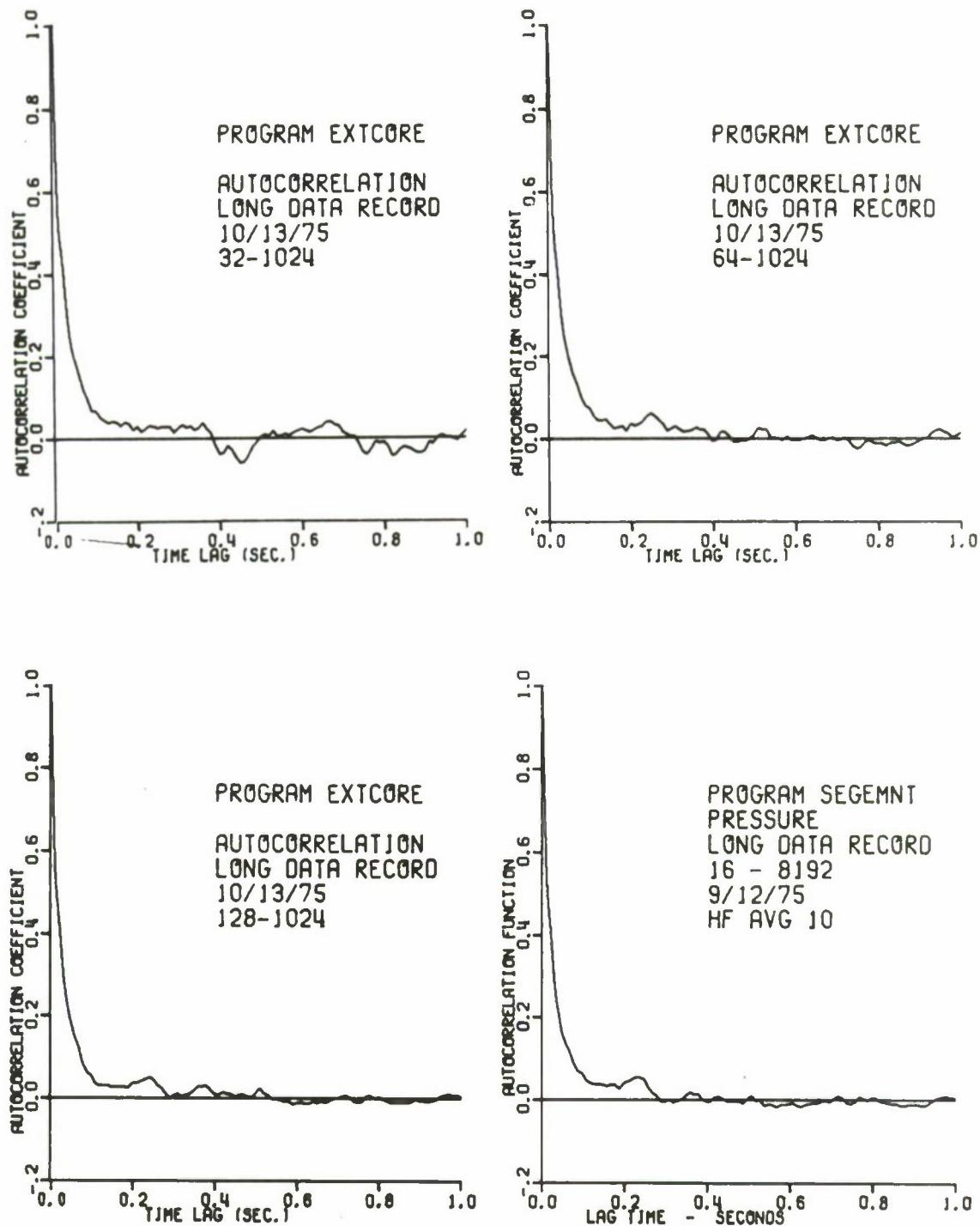
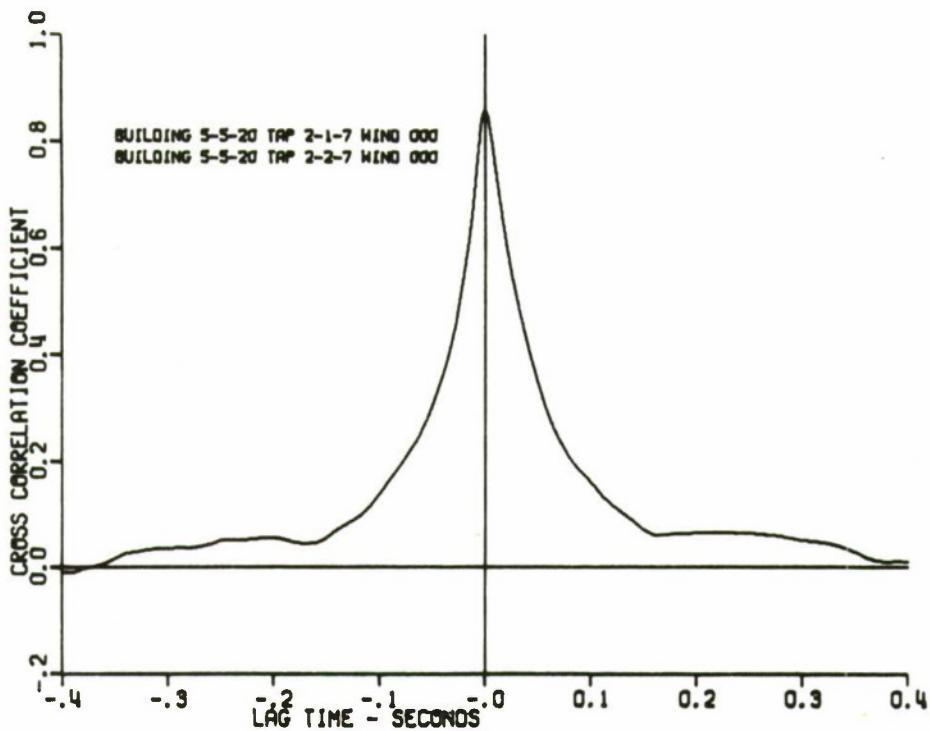
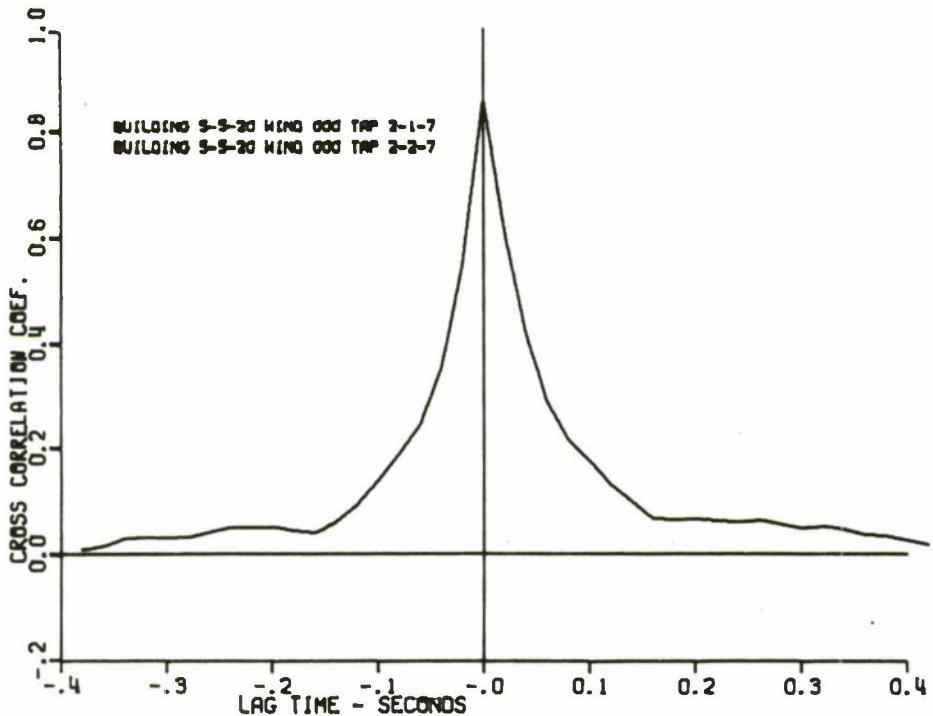


FIGURE 13. AUTOCORRELATIONS--PROGRAM EXTCORE.



(a) FFT COMPUTATION



(b) DIRECT COMPUTATION

FIGURE 14. COMPARISON OF CROSS-CORRELATION FUNCTIONS--DIRECT AND FFT COMPUTATION.

## APPENDICES

- A1 SUBROUTINE FOURT  
IBM contributed Program No. 3600-13.4001
- A2 SUBROUTINE FOR2D  
IBM contributed Program No. 3600-13.4006
- B1 PROGRAM CHECK
- B2 PROGRAM SEGEMNT
- B3 PROGRAM EXTCORE
- B4 PROGRAM CSPECT2
- B5 PROGRAM CSPECT3

## SUBROUTINE FFT (DATA,NN,NDIM,ISIGN,IFORM,WORK)

THE COOLEY-TUKEY FAST FOURIER TRANSFORM IN USASI BASIC FORTRAN

```

C C
C C TRANSFORM(K1,K2,...) = SUM(DATA(J1,J2,...)*EXP((ISIGN*2*PI*SQRT(-1))*K1*(J1-1)*(K1-1)/NN(1)*(J2-1)*(K2-1)/NN(2)+...))
C C J1, K1 PFTWFFN 1 AND NN(1), J2, K2 BETWEEN 1 AND NN(2). SUMMED FOR ALL.
C C THERE IS NO LIMIT TO THE NUMBER OF SUBSCRIPTS. DATA IS A
C C MULTIDIMENSIONAL COMPLEX ARRAY WHOSE REAL AND IMAGINARY
C C PARTS ARE ADJACENT IN STORAGE. SUCH AS FORTRAN IV PLACES THEM.
C C IF ALL IMAGINARY PARTS ARE ZERO (DATA ARE DISGUISED REAL). SFT
C C IFORM TO ZFRO TO CUT THE RUNNING TIME BY UP TO FORTY PERCENT.
C C OTHERWISE, IFORM = +1. THE LENGTHS OF ALL DIMENSIONS ARE
C C STORED IN ARRAY NN. OF LENGTH NDIM. THEY MAY BE ANY POSITIVE
C C INTEGERS. THE THF PROGRAM RUNS FASTER ON COMPOSITE INTEGERS. AND
C C ESPECIALLY FAST ON NUMBERS RICH IN FACTORS OF TWO. ISIGN IS +1
C C OR -1. IF A -1 TRANSFORM IS FOLLOWED BY A +1 ONE (OR A +1
C C BY A -1) THE ORIGINAL DATA REAPPEAR, MULTIPLIED BY NTOT (=NN(1))*NN(2)*...
C C TRANSFORM VALUES ARE ALWAYS COMPLEX, AND ARE RETURNED IN
C C IN ARRAY DATA. REPLACING THE INPUT. IN ADDITION, IF ALL
C C DIMENSIONS ARE NOT POWERS OF TWO, ARRAY WORK MUST BE SUPPLIED.
C C COMPLEX OF LENGTH EQUAL TO THE LARGEST NON 2**K DIMENSION.
C C OTHERWISE, REPLACE WORK BY ZERO IN THE CALLING SEQUENCE.
C C NORMAL FORTRAN DATA OROUNDING IS EXPECTED. FIRST SUBSCRIPT VARYING
C C IN ALL SUBSCRIPTS BEGIN AT ONE.
```

```

C C
C C RUNNING TIME IS MUCH SHORTER THAN THE NAIVE NTOT**2, BEING
C C GIVEN BY THE FOLLOWING FORMULA. DECOMPOSE NTOT INTO
C C  $2^{*K_2} * 3^{*K_3} * 5^{*K_5} * \dots$ . LET SUM2 =  $2^{*K_2}$ , SUMF =  $3^{*K_3} + 5^{*K_5}$ 
C C  $+ \dots$  AND NF =  $K_3 + K_5 + \dots$ . THE TIME TAKEN BY A MULTI-
C C DIMENSIONAL TRANSFORM ON THESE NTOT DATA IS  $T = T_0 + NTOT * (T_1 +$ 
C C  $T_2 * SUM2 + T_3 * SUMF + T_4 * NF)$ . ON THE CDC 3300 (FLOATING POINT AD) TIME
C C OF SIX MICROSECONDS.  $T = 3000 + NTOT * (500 + 43 * SUM2 + 68 * SUMF +$ 
C C  $320 * NF)$  MICROSECONDS ON COMPLEX DATA. IN ADDITION, THE
C C ACCURACY IS GREATLY IMPROVED, AS THE RMS RELATIVE ERROR IS
C C ROUNDED BY  $3^{*2} * (-R) * SUM(FACTOR(j)**1.5)$ . WHERE R IS THE NUMBER
C C OF BITS IN THE FLOATING POINT FRACTION AND FACTOR(j) ARE THE
C C PRIME FACTORS OF NTOT.
```

```

C C
C C PROGRAM BY NORMAN PRENNER FROM THE BASIC PROGRAM BY CHARLES
C C RADFP. RALPH ALTER SUGGESTED THE IDEA FOR THE DIGIT REVERSAL.
C C MIT LINCOLN LABORATORY. AUGUST 1967. THIS IS THE FASTEST AND MOST EFFICIENT
C C VERSATILE VERSION OF THE FFT KNOWN TO THE AUTHOR. SHORTER PROGRAMS
C C FOURIER AND FOURIER TRANSFORM LENGTHS TO POWERS OF TWO. FFTT0430
C C SEE-- IEEE AUDIO TRANSACTIONS (JUNE 1967), SPECIAL ISSUE ON FFT.
C C THE DISCRETE FOURIER TRANSFORM PLACES THREE RESTRICTIONS UPON THE
C C DATA.
C C I. THE NUMBER OF INPUT DATA AND THE NUMBER OF TRANSFORM VALUES
```

```

FFT0490
FFT0500
FFT0510
FFT0520
FFT0530
FFT0540
FFT0550
FFT0560
FFT0570
FFT0580
FFT0590
FFT0600
FFT0610
FFT0620
FFT0630
FFT0640
FFT0650
FFT0660
FFT0670
FFT0680
FFT0690
FFT0700
FFT0710
FFT0720
FFT0730
FFT0740
FFT0750
FFT0760
FFT0770
FFT0780
FFT0790
FFT0800
FFT0810
FFT0820
FFT0830
FFT0840
FFT0850
FFT0860
FFT0870
FFT0880
FFT0890
FFT0900
FFT0910
FFT0920
FFT0930
FFT0940
FFT0950

MUST BE THE SAME.
2. BOTH THE INPUT DATA AND THE TRANSFORM VALUES MUST REPRESENT
EQUISPACED POINTS IN THEIR RESPECTIVE DOMAINS OF TIME AND
FREQUENCY. CALLING THESE SPACINGS DELTAT AND DELTAF. IT MUST BE
TRUE THAT DELTAF=2*PI/(NN(1)*DELTAT). OF COURSE, DELTAT NEED NOT
BE THE SAME FOR EVERY DIMENSION.
3. CONCEPTUALLY AT LEAST. THE INPUT DATA AND THE TRANSFORM OUTPUT
REPRESENT SINGLE CYCLES OF PERIODIC FUNCTIONS.

EXAMPLE 1. THREE-DIMENSIONAL FORWARD FOURIER TRANSFORM OF A
COMPLEX ARRAY DIMENSIONED 32 BY 25 BY 13 IN FORTRAN IV.
DIMENSION DATA(32,25,13),WORK(50),NN(3)
COMPLEX DATA
DATA NN/32,25,13/
DC 1 I=1,32
DC 1 J=1,25
DO 1 K=1,13
 1 DATA(I,J,K)=COMPLEX VALUF
CALL FOURT(DATA,NN,3,-1,1,WORK)

EXAMPLE 2. ONE-DIMENSIONAL FORWARD TRANSFORM OF A REAL ARRAY OF
LENGTH 64 IN FORTRAN II.
DIMENSION DATA(2,64)
DC 2 I=1,64
DATA(1,I)=REAL PART
DATA(2,I)=0.
CALL FOURT(DATA,64,1,-1,0,0)

DIMENSION DATA(1,NN(1)),IFACT(32),WORK(1)
WR = 0.0
WI = 0.0
WSTPR = 0.0
WSTPI = 0.0
TWOPI=6.283185307
1 IF(NN(1)-1)920,1,1
NTOT=2
DC 2 IDIM=1,NDIM
IF(NN(IDIM))920,920,2
 2 NTOT=NTOT*NN(IDIM)
MAIN LOOP FOR EACH DIMENSION
NP1=2
DO 910 IDIM=1,NDIM
  N=NN(IDIM)
  NP2=NP1*N
  IF(N-1)920,900,5
    FACTOR N
  M=N
  5
```

```

FFTTT0960
FFTTT0970
FFTTT0980
FFTTT0990
FFTTT1000
FFTTT1010
FFTTT1020
FFTTT1030
FFTTT1040
FFTTT1050
FFTTT1060
FFTTT1070
FFTTT1080
FFTTT1090
FFTTT1100
FFTTT1110
FFTTT1120
FFTTT1130
FFTTT1140
FFTTT1150
FFTTT1160
FFTTT1170
FFTTT1180
FFTTT1190
FFTTT1200
FFTTT1210
FFTTT1220
FFTTT1230
FFTTT1240
FFTTT1250
FFTTT1260
FFTTT1290
FFTTT12A0
FFTTT1300
FFTTT1310
FFTTT1320
FFTTT1330
FFTTT1340
FFTTT1350
FFTTT1360
FFTTT1370
FFTTT1380
FFTTT1390
FFTTT1400
FFTTT1410
FFTTT1420
FFTTT1430
FFTTT1440
FFTTT1450
FFTTT1460

NTWO=NPI
IF=1
IDIV=2
IQUOT=M/IDIV
IREM=M-IDIV*IQUOT
IF(IQUOT-IDIV)<0.11•11
IF(IREM)>0.12•20
NTWO=NTWO+NTWO
M=IQUOT
GO TO 10
IDIV=3
IQUOT=M/IDIV
IREM=M-IDIV*IQUOT
IF(IQUOT-IDIV)<0.31•31
IF(IREM)>0.32•40
IFACT(IF)=IDIV
IF=IF+1
M=IQUOT
GO TO 30
IDIV=IDIV+2
GO TO 30
IF(IREM)>0.51•60
NTWO=NTWO+NTWO
GO TO 70
IFACT(IF)=M

C SEPARATE FOUR CASES--
C 1. COMPLEX TRANSFORM FOR REAL TRANSFORM FOR THF 4TH•5TH•FTC.
C DIMESTNS.
C 2. REAL TRANSFORM FOR THE 2ND OR 3RD DIMENSION. METHOD--_
C TRANSFORM HALF THE DATA. SUPPLYING THF OTHER HALF BY CON-
C JUGATE SYMMETRY.
C TRANSFORM HALF THE DATA AT EACH STAGF. SUPPLYING THE OTHER
C 3. REAL TRANSFORM FOR THE 1ST DIMENSION. N ODD. METHOD--_
C HALF BY CONJUGATE SYMMETRY.
C 4. REAL TRANSFORM FOR THE 1ST DIMENSION. N EVEN. METHOD--_
C TRANSFORM A COMPLEX ARRAY OF LENGTH N/2 WHOSE REAL PARTS
C ARE THF EVEN NUMBERED REAL VALUES AND WHOSE IMAGINARY PARTS
C ARE THF ODD NUMBERED REAL VALUES. SEPARATE ARR SUPPLY
C THF SECOND HALF BY CONJUGATE SYMMETRY.
C
C NON2=NPI*(NP2/NTWO)
ICASE=1
IF(IDIM=4)71•90•90
IF(IIFORM)72•72•90
ICASE=2
IF(IDIM=1)73•73•90
ICASE=3
IF(NTWO-NPI)90•90•74
ICASE=4
NTWO=NTWO/2

```

```

N=N/?
NP2=NP2/?
NTOT=NTOT/?
I=3
  DO 80 J=2,NTOT
    DATA(J)=DATA(1)
  I=I+2
  80  I1RNG=NP1
    IF(ICASF-2)100,95,100
  95  I1RNG=NP0*(1+NPREF/2)
C
C   SHUFFLE ON THE FACTORS OF TWO IN N. AS THE SHIFTING
C   CAN BE DONE BY SIMPLE INTERCHANGE, NO WORKING ARRAY IS NEEDED
C
  100 IF(NT-NP1)600,600,110
  110 NP2HF=NP2/2
J=1
  DC 150 J2=1, NP2*NON2
  IF (J-12)120,130,130
  120  I1MAX=I2+NON2-2
    DO 125 I1=I2,I1MAX,2
    DO 125 I3=I1,NTOT,NP2
      J3=J+I3-I2
      TEMPQ=DATA(I3)
      TEMPJ=DATA(I3+1)
      DATA(I3)=DATA(J3)
      DATA(I3+1)=DATA(J3+1)
      DATA(J3)=TEMPH
      DATA(J3+1)=TEMP1
      M=NP2HF
  130  IF (J-M)150,150,145
  140  J=J-M
  145  M=M/?
  150  IF (M-NON2)150,140,140
      J=J+M
C
C   MAIN LOOP FOR FACTORS OF TWO. PERFORM FOURIER TRANSFORMS OF
C   LENGTH FOUR, WITH ONE OF LENGTH TWO. IF NEEDED. THE TWIDDLE FACTOR FFT1440
C   W=EXP(SIGNS*PI*SINT(-1)*M/(4*MMAX)). CHECK FOR W=SIGN(SIGN(-1)*CONJUGATE(W)).
C   AND PEPFAT FOR W=SIGN(SIGN(-1)*CONJUGATE(W)).
C
  NON2T=NON2*NON2
  1PAP=NTWO/NP1
  1F(1PAP-2)350,330,320
  320  1PAP=1PAP/4
    GO TO 310
  310  DO 340 I1=1,1IPNG,2
    DC 340 J3=1,NON2*NP1
    DC 340 K1=J3,NTOT,NON2
      K2=K1+NON2
      TEMP=DATA(IK2)

```

```

TEMP1=DATA(K2+1)
DATA(K2)=DATA(K1)-T*MPW
DATA(K2+1)=DATA(K1+1)-TEMP1
DATA(K1)=DATA(K1)+T*MPR
DATA(K1+1)=DATA(K1+1)+T*MP1
MMAX=NON2
340 IF (MMAX-NP2HF) 370,600,600
      LMAX=MAX0(NON2T,MMAX/2)
350 IF (MMAX-NON2) 405,405,340
      THETA=-TWOPI*FLOAT(NON2)/F1 DATA(4*MMAX)
      IF (ISIGN) 400,390,390
      THETA=-THETA
      WR=COS(THETA)
      WI=SIN(THETA)
      WTPPE=-2.*WI*WI
      WSTPI=2.*WR*WI
      DO 570 L=NON2,LMAX,NON2T
      M=L
      IF (MMAX-NON2) 420,420,410
      WR=WR*WR-WI*WI
      W2I=2.*WP*WI
      W3I=WP*WI+W2I*WP
      W3R=WP*WR-W2I*WI
      DC 530 I1=1,T1RNG,2
      DO 530 J3=I1,NON2,NP1
      KMIN=J3+IPA4*W
      IF (MMAX-NON2) 430,430,440
      KMIN=J3
      430 KDIF=IPAR*MMAX
      440 KSTEP=4*KDIF
      450
      DO 520 K1=KMIN,NTOT,KSTEP
      K2=K1+KDIF
      K3=K2+KDIF
      K4=K3+KDIF
      IF (MMAX-NON2) 460,460,440
      U1R=DATA(K1)+DATA(K2)
      U1I=DATA(K1+1)+DATA(K2+1)
      U2P=DATA(K3)+DATA(K4)
      U2I=DATA(K3+1)+DATA(K4+1)
      U3P=DATA(K1)-DATA(K2)
      U3I=DATA(K1+1)-DATA(K2+1)
      IF (ISIGN) 470,475,475
      U4Q=DATA(K3+1)-DATA(K4+1)
      U4I=DATA(K4)-DATA(K3)
      GO TO 510
      U4R=DATA(K4+1)-DATA(K3+1)
      U4I=DATA(K3)-DATA(K4)
      GO TO 510
      480 T2R=WP*DATA(K2)-WI*DATA(K2+1)
      T2I=WR*DATA(K2+1)+WI*DATA(K2)
      T3R=WR*DATA(K3)-WI*DATA(K3+1)

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```

T3I=WH*DATA(K3+1)+W1*DATA(K3)
T4R=W3R*DATA(K4)-W3I*DATA(K4+1)
T4I=W3R*DATA(K4+1)+W3I*DATA(K4)
U1R=DATA(K1)+T2R
U1I=DATA(K1+1)+T2I
U2R=T3R+T4R
U2I=T3I+T4I
U3R=DATA(K1)-T2R
U3I=DATA(K1+1)-T2I
IF(ISIGN)490,500,500

490   U4R=T3I-T4I
      U4I=T4R-T3R
      GO TO 510
      U4R=T4I-T3I
      U4I=T3R-T4R
      DATA(K1)=U1R+U2R
      DATA(K1+1)=U1I+U2I
      DATA(K2)=U3R+U4R
      DATA(K2+1)=U3I+U4I
      DATA(K3)=U1R-U2R
      DATA(K3+1)=U1I-U2I
      DATA(K4)=U3R-U4R
      DATA(K4+1)=U3I-U4I
      KMIN=4*(KMIN-J3)+J3
      KDIF=KSTEP
      IF(KDIF-NP2)450,530,530
      COUNTNUF
      M=MMAX-M
      IF(ISIGN)540,550,550
      TEMPQ=WR
      WR=-WI
      WI=-TEMPR
      GC TO 560
      TEMPZ=WA
      WA=WI
      WI=TFMPR
      IF(M-LMAX)565,565,410
      TEMPZ=WR
      WR=WR*WSTPR-WI*WSTPI+WP
      WI=WI*WSTPR+TEMPR*WSTPI+WI
      IPAR=3-IPAR
      MMAX=MMAX+MMAX
      GO TO 360

530   MMAX-M
      IF(ISIGN)540,550,550
      TEMPQ=WR
      WR=-WI
      WI=-TEMPR
      GC TO 560
      TEMPZ=WA
      WA=WI
      WI=TFMPR
      IF(M-LMAX)565,565,410
      TEMPZ=WR
      WR=WR*WSTPR-WI*WSTPI+WP
      WI=WI*WSTPR+TEMPR*WSTPI+WI
      IPAR=3-IPAR
      MMAX=MMAX+MMAX
      GO TO 360

C     MAIN LOOP FOR FACTORS NOT EQUAL TO TWO. APPLY THE TWIDDLE FACTOR
C     W=EXP((ISIGN)*2*PI*SQRT((-1)*(J2-1)*(J1-J2)/(NP2*IFPL)). THEN
C     PERFORM A FOURIER TRANSFORM OF LENGTH IFACT(IF), MAKING USE OF
C     CONJUGATE SYMMETRIES.
C
C     IF(NTWO-NP2)605,700,700
C
C     FFTT2490
C     FFTT2500
C     FFTT2510
C     FFTT2520
C     FFTT2530
C     FFTT2540
C     FFTT2550
C     FFTT2560
C     FFTT2570
C     FFTT2580
C
C     FFTT2590
C     FFTT2600
C     FFTT2610
C     FFTT2620
C     FFTT2630
C     FFTT2640
C     FFTT2650
C     FFTT2660
C     FFTT2670
C     FFTT2680
C     FFTT2690
C     FFTT2700
C     FFTT2710
C     FFTT2720
C     FFTT2730
C     FFTT2740
C     FFTT2750
C     FFTT2760
C     FFTT2770
C     FFTT2780
C     FFTT2790
C     FFTT2800
C     FFTT2810
C     FFTT2820
C     FFTT2830
C     FFTT2840
C     FFTT2850
C     FFTT2860
C     FFTT2870
C     FFTT2880
C     FFTT2890
C     FFTT2900
C     FFTT2910
C     FFTT2920
C     FFTT2930
C     FFTT2940
C     FFTT2950
C     FFTT2960
C     FFTT2970
C     FFTT2980

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```

605      IFP1=NONN2
       IF=1
       NP1HF=NP1/2
       IFP2=IFP1/IFACT(IF)
610      J1RNG=NP2
           IF ((ICASF=3) .AND. 612 .GT. 611 .GT. 612)
           J1RNG=(NP2+IFP1)/2
611      J2STP=NP2/IFACT(IF)
           J1R62=(J1RNG+IFP2)/2
612      J2MIN=1+IFP2
           IF ((IFP1-NP2) .GT. 615 .GT. 640 .GT. 640)
           DO 635 J2=J2MIN*IFP1*IFP2
               THETA=-TWOPI*FLOAT((J2-1)/FLOAT(NP2))
           IF ((SIGN) 625 .GT. 620 .GT. 620)
               THETA=-THETA
               SINTH=SIN(THFTA/2.)
               WSTPI=SIN(THFTA)
               WSTPRE=2.*SINTH*SINTH
               WSTPI=WSTPI
               WR=WSTPR+1.
615      WI=WSTPI
           J1MIN=J2+IFP1
           DO 635 JI=J1MIN.J1RNG*IFP1
               I1MAX=JI+1.I1RNG-2
               DO 630 I1=JI+1.I1MAX+2
               DO 630 I3=I1.NTOT.NP2
                   J3MAX=I3+IFP2-NP1
                   DO 630 J3=I3.J3MAX.NP1
                       TEMP=DATA(J3)
                       DATA(J3)=DATA(J3)*WW-DATA((J3+1)*WI
                           DATA(J3+1)=TEMP*WI+DATA(J3+1)*WI
                           TEMP=WR
                           WR=WR+WSTPR-WI*WSTPI+WI
616      WI=TEMP*WSTPI+WI*WSTPP+WI
               THETA=-TWOPI*FLOAT(IFACT(IF))
               IF ((SIGN) 650 .GT. 645 .GT. 645)
                   THETA=-THETA
                   SINTH=SIN(THFTA/2.)
                   WSTPRE=2.*SINTH*SINTH
                   WSTPI=SIN(THFTA)
                   KSTFP=2*N/IFACT(IF)
                   KRANG=KSTFP*(IFACT(IF)/2)+1
635      DO 698 J1=1.I1RNG+2
640      DO 698 I3=I1.NTOT.NP2
645      DO 690 KMIN=1.KRANG.KSTEP
650      J1MAX=I3+J1RNG-IFP1
           DO 680 JI=I3.J1MAX*IFP1
               J3MAX=JI+IFP2-NP1
               DO 680 J3=JI.J3MAX.NP1
                   J2MAX=J3+IFP1-IFP2
                   K=KMIN+(J3-J1+(JI-13)/IFACT(IF))/NP1HF
                   IF ((KMIN-1) .GT. 655 .GT. 655)

```

```

SUMR=0.
SUM I=0.
DO 660 J2=J3,J2MAX,1 IFP?
SUMR=SUMR+DATA(J2)
SUMI=SUMI+DATA(J2+1)
WORK(K)=SUMR
WORK(K+1)=SUMI
60 TO 680
665 KCONJ=K+2*(N-KMIN+1)
J2=J2MAX
SUMR=DATA(J2)
SUMI=DATA(J2+1)
OLDSR=0.
OLDST=0.
J2=J2-IFP2
TEMPR=SUMR
TFMPI=SUMI
SUMR=TWOWR*SUMR-OLDSR+DATA(J2)
SUMI=TWOWR*SUMI-OLDSI+DATA(J2+1)
OLDSR=TFMRH
OLDSI=TFMPI
J2=J2-IFP2
IF (J2-J3) 675,675,677
TEMPR=WR*SUMR-OLDSR+DATA(J2)
TEMPI=WI*SUMI
WORK(K)=TFMPQ-TEMPI
WORK(KCONJ)=TEMRR+TFMPI
TEMRR=WR*SUMI-OLDSI+DATA(J2+1)
TFMPI=WI*SUMR
WORK(K+1)=TEMPR+TEMPI
WORK(KCONJ+1)=TEMRR-TFMRI
CONTINUE
IF (KMIN-1) 685,685,686
685 WR=WSTPR+1.
WI=WSTRI
60 TO 690
686 TEMP=WR
WR=WSTPR-WSTPR-WI*WSTPI+WR
WI=TFMPR*WSTPI+WI*WSTPR+WI
TWOWR=WR+WR
IF (ICASE=3) 692,691,692
IF (IFR1-NP2) 695,692,692
691 K=1
692 I2MAX=I3+NR2-NR1
DC 693 I2=I3+I2MAX+NP1
DATA(I2)=WORK(K)
DATA(I2+1)=WORK(K+1)
693 K=K+2
60 TO 698
C
C      COMPLETF A RFAL TRANSFORM IN THE 1ST DIMENSION, N ODD, RY CON-
C

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```

C JUGATE SYMMETRIES AT EACH STAGE.
C
695   J3MAX=I3+IFP2-NP1
      DC 697  J3=I3•J3MAX•NP1
      J2MAX=J3+NP2-J2STP
      DO 697  J2=J3•J2MAX•J2STP
      J1MAX=J2+J1RG2-IFP2
      J1CNJ=J3+J2MAX+J2STP-J2
      DO 697  J1=J2+J1MAX•IFP2
      K=I+J1-I3
      DATA(J1)=WORK(K)
      DATA(J1+1)=WORK(K+1)
      IF (J1-J2)697•697.696
      DATA(J1CNJ)=WORK(K)
596     DATA(J1CNJ+1)=--WORK(K+1)
      DATA(J1CNJ)=J1CNJ-IFP2
      CONTINUE
      IF=IF+1
      IFP1=IFP2
      IF(IFP1-NP1)700•700•610
C COMPLETE A REAL TRANSFORM IN THE 1ST DIMENSION. N FVFN. HY CON-
C JUGATE SYMMETRIES.
C
697   GO TO (900,800,900•701)•ICASF
      NHALF=N
701   N=N+N
      THETA=-TWOPI/FLOAT(N)
      IF (ISIGN)703•702•702
      THETA=THETA
      SINTH=SIN(THETA/2.)
      WSTPR=-2.*SINTH*SINTH
      WSTPI=SIN(THETA)
      WR=WSTPR+1.
      WI=WSTPI
      IWIN=3
      JWIN=2*NHALF-1
      GO TO 725
710   J=JWIN
      DO 720  I=IWIN,NTOI•NP2
      SUMR=(DATA(I)+DATA(J))/2.
      SUMI=(DATA(I+1)+DATA(J+1))/2.
      DIFR=(DATA(I)-DATA(J))/2.
      DIFI=(DATA(I+1)-DATA(J+1))/2.
      TEMP=WR*SUMI+WI*DIFR
      TEMP1=WI*SUMI-WR*DIFR
      DATA(I)=SUMR+TEMPR
      DATA(I+1)=DIFI+TEMP1
      DATA(J)=SUMR-TEMPR
      DATA(J+1)=-DIFI+TEMP1
      J=J+NP2
      FFTT4010
      FFTT4020
      FFTT4030
      FFTT4040
      FFTT4050
      FFTT4060
      FFTT4070
      FFTT4080
      FFTT4090
      FFTT4100
      FFTT4110
      FFTT4120
      FFTT4130
      FFTT4140
      FFTT4150
      FFTT4160
      FFTT4170
      FFTT4180
      FFTT4190
      FFTT4200
      FFTT4210
      FFTT4220
      FFTT4230
      FFTT4240
      FFTT4250
      FFTT4260
      FFTT4270
      FFTT4280
      FFTT4290
      FFTT4300
      FFTT4310
      FFTT4320
      FFTT4330
      FFTT4340
      FFTT4350
      FFTT4360
      FFTT4370
      FFTT4380
      FFTT4390
      FFTT4400
      FFTT4410
      FFTT4420
      FFTT4430
      FFTT4440
      FFTT4450
      FFTT4460
      FFTT4470
      FFTT4480
      FFTT4490
      FFTT4500
      FFTT4510

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```

IMIN=IMIN+2
JMIN=JMIN-2
TEMP=WR
WR=WR*WSTPR-WI*WSTPI+WR
WI=TFMPR*WSTPI+WI*WSTPR+WI
IF (IMIN-JMIN)710•730•740
IF (ISIGN)731•740•740
DO 735 I=IMIN•NTOT•NP2
DATA(I+1)=DATA(I+1)
735 NP2=NP2+NP2
NTOT=NTOT+NTOT
J=NTOT+
IMAX=NTOT/2+1
IMIN=IMAX-2*NHALF
I=IMIN
60 TO 755
DATA(J)=DATA(I)
DATA(J+1)=-DATA(I+1)
I=I+2
J=J-2
IF (I-IMAX)750•760•760
DATA(J)=DATA(IMIN)-DATA(IMIN+1)
DATA(J+1)=0.
IF (I-J)770•780•780
DATA(J)=DATA(I)
DATA(J+1)=DATA(I+1)
770 I=I-2
J=J-?
IF ((I-IMIN)775•775•765
DATA(J)=DATA(IMIN)+DATA(IMIN+1)
DATA(J+1)=0.
IMAX=IMIN
60 TO 745
DATA(1)=DATA(1)+DATA(2)
DATA(2)=0.
60 TO 900
C
C COMPLETE A RFL TRANSFORM FOR THE 2ND OR 3RD DIMENSION HY
C CONJUGATE SYMMETRIES.
C
C
800 IF ((IRNG-NP1)A05•900•900
A05 DO A60 I3=1•NTOT•NP2
I2MAX=I3•NP2-NP1
DO A60 I2=I3•I2MAX•NP1
IMIN=I2+IRNG
IMAX=I2+NP1-2
JMAX=2*I3+NP1-IMIN
IF (I2-I3)820•820•810
A10 JMAX=JMAX+NP2
A20 IF (INIM-2)A50•A50•A30
A30 J=JMAX+NP0
FFTT4520
FFTT4530
FFTT4540
FFTT4550
FFTT4560
FFTT4570
FFTT4580
FFTT4590
FFTT4600
FFTT4610
FFTT4620
FFTT4630
FFTT4640
FFTT4650
FFTT4660
FFTT4670
FFTT4680
FFTT4690
FFTT4700
FFTT4710
FFTT4720
FFTT4730
FFTT4740
FFTT4750
FFTT4760
FFTT4770
FFTT4780
FFTT4790
FFTT4800
FFTT4810
FFTT4820
FFTT4830
FFTT4840
FFTT4850
FFTT4860
FFTT4870
FFTT4880
FFTT4890
FFTT4900
FFTT4910
FFTT4920
FFTT4930
FFTT4940
FFTT4950
FFTT4960
FFTT4970
FFTT4980
FFTT4990
FFTT5000
FFTT5010
FFTT5020

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```
DO R40 I=IMIN,IMAX,2
  DATA(I)=DATA(J)
  DATA(I+1)=-DATA(J+1)
  J=J-2
R40
J=JMAX
DO R60 I=IMIN,IMAX,NP0
  DATA(I)=DATA(J)
  DATA(I+1)=-DATA(J+1)
  J=J-NP0
R60
C   FND OF LOOP ON EACH DIMENSTON
C
  NP0=NP1
  NP1=NP2
  NPROV=N
  RFTURN
END
#
FFT5030
FFT5040
FFT5050
FFT5060
FFT5070
FFT5080
FFT5090
FFT5100
FFT5110
FFT5120
FFT5130
FFT5140
FFT5150
FFT5160
FFT5170
FFT5180
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1      SUBROUTINE F0R2D (IDATA•N•NDIM•ISIGN•IFORM•WORK•NELEM)          F20
2      FOR2D COMPUTES A DISCRETF FOURIER TRANSFORM BY THE COOLEY-TUKEY   F20
3      ALGORITHM. THE ARRAY IS COMPLEX. MULTI-DIMENSIONAL AND KEPT ON    F20
4      DIRECT ACCESS STORAGE. THE NUMBER OF DATA IN EACH DIMENSION MUST   F20
5      BE A POWER OF TWO. RUNNING TIME IS PROPORTIONAL TO NTOT*.        F20
6      LOG2(NTOT)* WHERE NTOT IS THE TOTAL NUMBER OF DATA. ORDINARY      F20
7      FOURIER TRANSFORM PROGRAMS RUN IN TIME NTOT**2. THE TRANSFORM     F20
8      IS DONE IN-PLACE ON THE DIRECT ACCESS STORAGE. AND AS MUCH OF THF     F20
9      TRANSFORM AS POSSIBLE IS DONE IN CORE. ENTIRELY IN-CORE.           F20
10     PROGRAMS ARE ALSO AVAILABLE. (FOURI. FOURG. FOURR AND FOURT).      F20
11     WRITTEN BY NORMAN ARFANEK. MIT LINCOLN LABORATORY. SEPTEMBER 1968. F20
12     SFE--IEEE AUDIT TRANSACTIONS (JUN 1967). A SPECIAL ISSUE ON THE F20
13     FAST FOURIER TRANSFORM.                                         F20
14
15     DIMENSION DATA(N(1)•N(2)•••••N(NDIM))•TRANSFORM(N(1)•••••N(NDIM)) F20
16     COMPLEX DATA•TRANSFORM                                         F20
17     DIMENSION N(NDIM)                                              F20
18     TRANSFORM(K1•K2•••••) = SUM(DATA(J1•J2•••••)*EXP((ISIGN*2*PI*I*
19     ((J1-1)*(K1-1)+(J2-1)*(K2-1)/N(2)+•••••)), SUMMED FOR ALL
20     J1 FROM 1 TO N(1), J2 FROM 1 TO N(2). FTC. • FOR ALL K1 FROM 1
21     TO N(1)• K2 FROM 1 TO N(2). FTC. • UP TO N(NDIM). NDIM IS
22     UNLIMITED. IF A SET OF DATA ARE ISIGN = -1 TRANSFORMED AND THEN
23     THE TRANSFORM VALUES +1 TRANSFORMED (OP VICE VERSA) THF RESULTS
24     WILL BE THE ORIGINAL DATA. MULTIPLIED BY NTOT = N(1)*•••••*N(NDIM).
25     IFORM MUST EQUAL 1. FUTURE VERSIONS OF FOR2D WILL MAKE USE OF IT. F2D
26     DATA ARF STORED ON DIRECT ACCESS STORAGE IN FILE NUMBER IDATA.     F2D
27     BROKEN INTO RECORDS OF LENGTH NELFM COMPLEX ELEMENTS (NELM MUST
28     BE A POWER OF TWO). TRANSFORM VALUES ARE RETURNED TO FILE IDATA. F2D
29     REPLACING THF INPUT.                                         F2D
30
31     THE USFR MUST SUPPLY TWO SUBROUTINES FOR I/O TO THF DIRECT
32     ACCESS STORAGE, DRFD AND DWRIT. THE CALLING SEQUENCE IS CALL
33     DXXXX(IDATA•IFC•HUFFH•NPEC•NELM). MEANING NREC RECORDS (EACH
34     NELFM COMPLEX ELEMENTS LONG) ARE TO BE TRANSMITTED BETWEEN STORAGE F2D
35     BUFFER HUFFH AND FILE NUMBER IDATA. RECORD NUMBER IHC (FROM 1
36     TO NTOT/NELM). THE HUFFEP SUPPLIED WILL BE PART OF ARHAY WORK.
37     WHICH MUST BE SUPPLIED BY THE USER. IT IS THREE RECORDS LONG.
38     FOR FASTEST RUNNING TIME, MAKE NELFM AS LARGE AS POSSIBLE.
39     DIMENSION N(1)• WORK(1)                                         F2D
40
41     NTOT=NTOT*N(NDIM)                                              F2D
42     NPRFV=1                                                       F2D
43
44     DO 20 IDIM=1•NDIM
45     NREM=NTOT/(N(NDIM)*NPRFV)
46     CALL BTRD (IDATA•NPREVN(NDIM)•NREM•WORK•NELM)
47     CALL COL2D (IDATA•NPREVN(NDIM)•NREM•ISIGN•WORK•NELM)
48     NPRFV=N(NDIM)*NPREV
49     RETURN

```

50-

F2D

56

```

SUBROUTINE SHUFFL (IDATA•NPREV•N•NRFM•HUFTR•NELFM)
C SHUFFL THE DATA BY BIT REVERSAL.
C DIMENSION DATA(NPREV•N•NRFM)
C COMPLEX DATA
C EXCHANGE DATA(J1•J2•REV•J3) WITH DATA(J1•J2•J3) • WHFRE J2REV-1
C IS THE RIT HFVERSL OF J2-1. FDR EXAMPLE. LET N = 32. THEN FOR
C J2-1 = 10011. J2REV-1 = 11001. ETC. DATA ARE COMPLEX AND STORED
C IN DIRECT ACCESS STORAGE. BUFR IS A COMPLEX BUFFER THREE RECORDS
C LONG. EACH RECORD OF LENGTH NELEM COMPLEX ELEMENTS. NELEM MUST
C BE LESS THAN HALF OF NRFM*N*NRFM. THE TOTAL NUMBER OF ELEMENTS.
C ELSE THE WHOLE TRANSFORM COULD BE DONE IN CORE. NPREV, N, NRFM
C AND NELFM MUST BE POWERS OF TWO.
C INTEGER INDICES MAY BECOME AS LARGE AS NPREV*N*NRFM*2.

DIMENSION BUFR(1)
IF (NELFM-NPREV) 10•10•20
DIMENSION DATA(NELFM•NPREV/NELFM•N•NRFM)
10 CALL SHUF (IDATA•NELEM•NPREV/NELEM•N•NRFM•HUFTR)
RETURN
20 IF (2*NELFM-N*NPREV) 50•30•30
C DIMENSION DATA(2*NELFM•(NPREV*N*NRFM)/(2*NRFM))
30 IP0=?
IP1=IP0*(2*NELEM)
IP2=IP0*(NPREV*N*NRFM)
DO 40 I2=1,IP2,IP1
IREC=1+(2*(I2-1))/IP1
CALL DREAD (IDATA•IPEC•BUFR•2•NRFM)
CALL RITR (BUFR•NPREV•N•(2*NELEM)/(NPREV*N))
CALL DWRTT (IDATA•IREC•BUFR•2•NRFM)
RETURN
50 NELRC=NELFM/NPREV
NREC=NELRC/NRFM
DIMENSION DATA(NPREV•NELRC•IREM•2•IPRD•NRFM)
DEFINE R = LDG2(NREC) AND F = LDG2(NELRC). THFN THE ENTIRE RIT
REVERSAL TAKES E STAGES. OF WHICH ND MORE THAN R+1 CAN TAKE FULL
PASSES THRU THF DATA.
IP0=2
IP1=IP0*NPREV
IP2=IP1*NELRC
IP5=IP2*NREC
IP6=IP5*NRFM
IP4=IP5
IF (IP4-IP1*MAX0(NELRC•NREC)) 170•170•70
C IP4=IP5/2**((ISTAG-1))
C IF ISTAG .GT. MIN(R•E) GO TO LAST TEST
70 IP3=IP4/2
C MERGE RECORDS DATA(I1•I2•I3•I5•I6) AND DATA(I1•I2•I3•2•I5•I6)
DO 160 I6=1,IP6,IP4
I3MAX=I6+IP3-IP2
DO 160 I3=I6,I3MAX,IP2

```

```

IREC0=1+(I3-1)/IP2
IREC1=IRFC0+IP3/IP2
IF (IREC1-IRFC0-1) .AU. MU. 90
SAVE SOME ACCESS TIME IF THE RECORDS ARE ADJACENT
C
80 CALL DRFAD (IDATA,IREC0,PUFFR(IP2+1)*2,NELFM)
GO TO 100
90 CALL DREAD (IDATA,IRFCU,PUFFR(IP2+1)*1,NELFM)
CALL DRFAD (IDATA,IREC1,PUFFR(2*IP2+1)*1,NELFM)
100 CALL MERGE (IUFFR(IP2+1),BUFFR(1),NPREV,NELRC)
C MERGE THE EVEN NUMBERED ELEMENTS
IUFFF=IP2+IP1+1
CALL MFRGE (IUFFR(IUFFF),BUFFR(IP2+1),NPREV,NELRC)
C MERGE THE ODD-NUMBERED ELEMENTS
IUFFF=1
C THE RECORDS ARE NOW IN PUFFRS 0 AND 1
IF (IP5-NRFC*IP3) 130•110•110
C IF ISTAG .LT. R, GOTO WRITE
110 IF (NREC-NFLRC) 120•130•130
C IF R .LT. E THEN DO SHUFC. ELSE WRITE OUT.
C SUBROUTINES SHUFC AND SHUFFD ARE MUTUALLY EXCLUSIVE--THE FIRST
C REQUIRES THAT NELRC BE GREATER THAN NREC. WHILE THF LATTER
C REQUIRES THE REVERSE.
120 CALL SHUFC (BUFFR(IP2+1),IUFFR(2*IP2+1),NPREV,NELRC,NREC)
C SHUFFLE BUFFF 1 AND PLACF INTO BUFFER 2
CALL SHUFC (BUFFR(1),BUFFR(IP2+1),NPREV,NELRC,NREC)
C SHUFFLE BUFFF 0 AND PLACE INTO BUFFER 1
IUFFF=IP2+1
C DATA ARE NOW IN BUFFRS 1 AND 2
130 IF (IREC1-IRFC0-1) 140•140•150
140 CALL DWRT (IDATA,IREC0,PUFFR(IUFFF)*2,NELFM)
60 TO 160
150 CALL DWRT (IDATA,IREC0,PUFFR(IUFFF)*1,NELFM)
IUFFF=IUFFF+IP2
CALL DWRT (IDATA,IREC1,PUFFR(IUFFF)*1,NELFM)
160 CONTINUE
IP4=IP3
GO TO 60
170 IF (NRFC-2*NFLRC) 190•190•140
C IF P •LF. F+1 RETURN.
180 CALL SHUFD (IDATA,NELFM*1,NHFC/NELRC*NREC,NELFM,RUFFR)
C BIT REVERSE THE RECORDS ON DISK.
190 RETURN
END

SUBROUTINE RTTRV (DATA,NPHFV,NPFM)
SHUFFL THE DATA BY BIT REVERSAL.
DIMENSION DATA(NPREV*NPEM)
COMPLEX DATA
C EXCHANGF DATA(J1,J4RFV,J5) WITH DATA(J1,J4,J5) FOR ALL J1 FROM 1
C TO NPREV. ALL J4 FROM 1 TO N (WHICH MUST BE A POWER OF TWO). AND
C ALL J5 FROM 1 TO NREM. J4REV-1 IS THE BIT REVERSAL OF J4-1.
E.G. RTTRV

```

```

C SUPPOSE N = 32. THEN FOR J4-1 = 10011. J4RFV-1 = 11001. ETC.
DIMENSION DATA(1)
IP0=?
IP1=IP0*NPFV
IP4=IP1*N
IP5=IP4*NRFM
I4RFV=1
I4RFV = 1 + (J4RFV-1)*IP1
DO 60 I4=1,IP4*IP1
I4 = 1 + (J4-1)*IP1
IF (I4-I4RFV) 10•30•30
10 I1MAX=I4+IP1-IP0
DO 20 I1=I4•I1MAX•IP0
I1 = 1 + (J1-1)*IP0*(J4-1)*IP1
DO 20 I5=I1•IP5•IP4
I5 = 1 + (J1-1)*IP0*(J4-1)*IP1+(J5-1)*IP4
I5RFV=I4REV+I5-I4
ISREV = 1 + (J1-1)*IP0+(J4RFV-1)*IP1+(J5-1)*IP4
TEMPR=DATA(I5)
TEMP1=DATA(I5+1)
DATA(I5)=DATA(I5REV)
DATA(I5+1)=DATA(I5REV+1)
DATA(I5REV)=TEMPR
DATA(I5RFV+1)=TEMP1
20 ADD ONE WITH DOWNWARD CARRY TO THE HIGH ORDER BIT OF J4REV-1.
C 30 IP2=IP4/2
40 IF (I4REV-IP2) 60•61•50
50 I4REV=I4REV-IP2
IP2=IP2/2
IF (IP2-IP1) 60•40•40
60 I4RFV=I4REV+IP2
RETURN
END

SURNROUTINE SHUFFD (IDATA•NLEM•NPREV•N•NHF•NHF)
SHUFFL THE RECORDS ON DIRECT ACCESS STORAGE BY BIT REVERSAL.
C DIMENSION DATA(NLEM•NPFV•N•NREM)
C COMPLEX DATA
C EXCHANGF DATA(J1•J2•J4RFV•J5) WITH DATA(J1•J2•J4•J5). WHERE
J4RFV-1 IS THE BIT REVERSAL OF J4-1. THIS CAN BE DONE BY AN
C EXCHANGE OF RECORDS.
DIMENSION RUFFR(1)
IP0=2
IP1=IP0*NLFM
IP2=IP1*NPREV
IP4=IP2*N
IP5=IP4*NREM
I4REV=1
DO 60 I4=1•IP4•IP2
IF (I4-I4RFV) 10•30•30
DO 20 I5=I4•IP5•IP4

```

```

I2MAX=IS+IP2-IP1 18
DO 20 I2=IS+I2MAX+IP1 19
I2PFV=I4PEV+I2-I4 20
IREC0=1+(I2-1)/IP1 21
IREC1=1+(I2PFV-1)/IP1 22
CALL DRFAD ((DATA,IREC0,HUFFR(1),1,NELFM) 23
CALL DRFAD ((DATA,IREC1,HUFFR(IP1+1),1,NELFM) 24
CALL DRWIT ((DATA,IREC1,HUFFR(1),1,NELFM) 25
CALL DRWIT ((DATA,IREC0,HUFFR(IP1+1),1,NELFM) 26
SHD 27
SHD 28
SHD 29
SHD 30
SHD 31
SHD 32
SHD 33
SHD 34
SHD 35-
END 35-  

IP3=IP4/2 24
IF (I4REV-IP3) 60+60+50 24
I4PFV=I4REV-IP3 30
IP3=IP3/2 30
IF (IP3-IP2) 60+40+40 31
I4REV=I4PEV+IP3 32
PFTURN 33
PFTURN 34
PFTURN 35-  

SUBROUTINE MERGE (FROM,TO,NPREV,NFLRC)
C MERGE TWO PCOPDS INTO ONE. 1
C DIMENSION FROM(NPREV*2*NFLRC)*TO(NPPEV*NFLRC) 2
C COMPLEX FPOW,TO 3
C TO(J1•J3)=FROM(J1•1•J3) 4
C DIMENSION FROM(1),TO(1) 5
IP0=2 6
IP1=IP0*NPFV 7
IP2=IP1*2 8
IP3=IP2*NFLRC 9
IT0=1 10
DO 10 I3=1,IP3,IP2 11
IIMAX=I3+IP1-IP0 12
DO 10 I1=I3,IIMAX,IP0 13
TO(IT0)=FPOW(I1) 14
TO(IT0+1)=FPOW(I1+1) 15
IT0=IT0+IP0 16
PFTURN 17
PFTURN 18
END 19-  

SUBROUTINE SHUFF (IP0M,TO,NPREV,NFLRC,NREC)
C SHUFFLE THE DATA IN COPE BY HIT REVERSAL. 1
C DIMENSION FROM(NPREV*NFLRC/NREC),TO(NPWFV*NREC*NFLRC/NREC) 2
C COMPLEX FPOW,TO 3
C TO(J1•J4,J3RFV)=FROM(J1•J3,J4) WHERE J3RFV-1 IS THE HIT PEVERSAL 4
C OF J3-1. 5
C DIMENSION FPOW(1),TO(1) 6
IP0=2 7
IP1=IP0*NPREV 8
IP3=IP1*(NFLRC/NREC) 9
IP4=IP3*NREC 10
IPREV=1 11
IPREV=1 12

```

```

00 40 I3=1+IP3+IP1
IT0=1+NPFM*(I3REV-1)
DO 10 I4=13,IP4+IP3
    IIMAX=I4+IP1+IP0
    DO 10 I1=14,IIMAX,IP0
        TO(IT0)=FRDN(I1)
        TC(IT0+1)=FRDN(I1+1)
        IT0=IT0+IP0
        ADD ONE WITH DOWNWARD CARRY TO THE HIGH ORDER BIT OF J3REV-1.
        IP2=IP3/2
        IF (I3REV-IP2) .GT. 40+40+30
        I3REV=I3REV-IP2
        IP2=IP2/2
        IF (IP2-IP1) .GT. 40+20+20
        I3REV=I3REV+IP2
        RETURN
END

```

```

10
C
20
30
40

```

```

SUBROUTINE COL2D (IDATA,NPREV,NNREM,ISIGN,BUFFR,NLFM)
DISCRETF FOURIER TRANSFORM OF LENGTH N. IN-PLACE COOLEY-TUKEY
ALGORITHM. BIT-REVERSED TO NORMAL ORDER. SAME-TUKEY PHASE SHIFTS.C2D
DIMENSION DATA(NPFM*N,NREM)
COMPLEX DATA
DATA(J1,K4,J5) = SUM (DATA (J1,J4+J5)*EXP ((ISIGN*2*PI*I*(J4-1)*
(K4-1)/N)) * SUMMED OVER J4 = 1 TO N FOR ALL J1 FROM 1 TO NPREV*
K4 FROM 1 TO N AND J5 FROM 1 TO NNREM. N MUST BE A POWER OF TWO.
METHOD--LET IPREV TAKE THE VALUES 1, 2 OR 4 OR 8, . . . N/16.
N/4 . . . N. THE CHOICE BETWEEN 2 OR 4, ETC., DEPENDS ON WHETHER N IS
A POWER OF FOUR. DEFINE IFACT = 2 OH 4, THE NEXT FACTOR THAT
IPREV MUST TAKE. AND IREM = N/(IFACT*IPREV). THEN--
DIMENSION DATA(NPREV,IPREV,IFACT,IREM,NREM)
COMPLEX DATA
DATA(J1,J2*K3,J4+J5) = SUM (DATA (J1,J2+J3,J4+J5)*EXP ((ISIGN*2*PI*I*
(K3-1)*((J3-1)/IFACT+(J2-1)/(IFACT*IPREV)))) * SUMMED OVER J3 = 1
TO IFACT FOR ALL J1 FROM 1 TO NPREV. J2 FROM 1 TO IPREV. K3 FROM
1 TO IFACT . . . J4 FROM 1 TO IREM AND J5 FROM 1 TO NNREM. THIS IS
A PHASE-SHIFTED DISCRETE FOURIER TRANSFORM OF LENGTH IFACT.
FACTORING N BY FOURS SAVES ABOUT TWENTY FIVE PERCENT OVER FACTOR-
ING BY TWOS. DATA MUST BE BIT-REVERSED INITIALLY.
IT IS NOT NECESSARY TO WRITE THIS SUBROUTINE INTO COMPLEX
NOTATION SO LONG AS THE FORTRAN COMPILER USED STORES REAL AND
IMAGINARY PARTS IN ADJACENT STORAGE LOCATIONS. IT MUST ALSO
STORE ARRAYS WITH THE FIRST SUBSCRIPT INCREASING FASTEST.
DIMENSION BUFFR(1)
TWOPI=6.2831853072*FLOAT(ISIGN)
IF (2*NLFM-NPREV) .GT. 30+10
DIMENSION DATA (2*NLFM, (NPREV*N*NREM)/(2*NLFM))
10
IP0=2
IP1=IP0*(2*NLFM)
IP2=IP0*(NPREV*N*NREM)
NMIN=MIN0(N, (2*NLFM)/NPREV)

```

```

NFIN=MAX(1,(2*NELEM)/(NPHEV*N))
DO 20 I2=1,IP2/IP1
IREC=1+(2*(I2-1))/IP1
CALL DREAD (IDATA,IREC,BUFFR,2*NELFM)
CALL CNDL2 (RUFFR,NPREF,NMIU,NFIN,ISIGN)
CALL DWRT (IDATA,IREC,BUFFR,2*NELFM)
20 DIMNSN DATA(NPREF,IPR0),Z,IREM,NREM)
IPO=?
IP1=IP0+NPRFV
IP4=IP1*N
IP5=IP4*NREM
NWORD=IP0*NFLEM
IP2=IP0*MAX(2*NELFM,NPRFV)
IF ((IP2-IP4) .GT. 100) 50,100,100
50 IP3=IP2*2
THETA=TWOPI/FLOAT(IP3/IP1)
SINHESIN(THE1A/2.)
WSTPRE=2.*SINTH*SINTH
WSTPI=SIN(THETA)
IRECO=1
IREC1=IPFC0+IP2/NWORD
IRECO AND IRFC1 ARE NEVER ADJACENT RECORDS. SO MUST RE READ AND
C WRITE SEPARATELY.
CALL DREAD (IDATA,IREC0,RUFFR(1)*1*NELFM)
CALL DRFAD (IDATA,IREC1,RUFFR(NWORD+1)*1*NELFM)
IELFM=1
I3MIN=1
DO 90 IS=1,IP5,IP3
WR=1.
WI=0.
I2MAX=IS+IP2-IP1
DO 90 I2=IS,12MAX,IP1
I1MAX=I2+IP1-IP0
DO 80 II=I2,I1MAX,IP0
IF (IELEM-NELEM) 70,70,60
IF ((IELEM-NELEM) 70,70,60
CALL DWRT (IDATA,IREC0,RUFFR(1)*1*NELFM)
CALL DWRT (IDATA,IREC1,RUFFR(NWORD+1)*1*NELEM)
IRECO=1+(II-1)/NWORD
IREC1=IPFC0+IP2/NWORD
CALL DRFAD (IDATA,IREC0,RUFFR(1)*1*NELFM)
CALL DRFAD (IDATA,IREC1,RUFFR(NWORD+1)*1*NELFM)
IELFM=1
I3MIN=1
I3A=II-I3MIN+
I3B=I3A+NWORD
TFMPR=WR*RUFFR(I3B)-WI*HUFFR(I3A+1)
TEMP1=WH*RUFFR(I3A+1)+WI*HUFFR(I3B)
BUFFR(I3B)=HUFFR(I3A)-TEMP1
RUFFR(I3A+1)=RUFFR(I3A+1)-TEMP1
RUFFR(I3A)=RUFFR(I3A)+TEMP1
HUFFR(I3A+1)=HUFFR(I3A+1)+TEMP1
60
70

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```

80 IFLEM=IFLEM+1
C2D 45
TEMPR=WR
C2D 86
WR=TMPR*WSTPP-WI*WSTP+WI*2
C2D 87
WI=TMPR*WSTPI+WI*WSTP+WI
C2D 88
CALL DWPIT (IDATA,IRECO,RUFFR(1),1*NFLFM)
C2D 89
CALL DWPIT (IDATA,IHECI,RUFFR(NWOR)+1,1*NELEM)
C2D 90
IP2=IP3
C2D 91
6C TO 40
C2D 92
RTURN
C2D 93
END
C2D 94-
C2D 95

C
C SUBROUTINE CNOL2 (DATA,NPHFV,N.NREM,ISIGN)
C DISCRETF FOURIER TRANSFORM OF LENGTH N. IN-PLACE COOLEY-TUKEY
C ALGORITHM. HIT-REVERSE TO NORMAL ORDER. SANDE-TUKEY PHASE SHIFTS.
C DIMENSION DATA(NPREV•N•NREM)
C COMPLEX DATA
C DATA(J1•K4•J5) = SUM(DATA(J1•J4•J5)*EXP((ISIGN*2*PI*I*(J4-1)*
C (K4-1)/N)) * SUMMED OVER J4 = 1 TO N FOR ALL J1 FROM 1 TO NPREV.
C K4 FROM 1 TO N AND J5 FROM 1 TO NREM. N MUST BE A POWER OF TWO.
C METHOD--LET IPREV TAKE THE VALUES 1, 2 OR 4 OR 8, ••• N/16.
C N/4, N. THE CHOICE BETWEEN 2 OR 4, ETC., DEPENDS ON WHETHER N IS
C A POWER OF FOUR. DEFINE IFACT = 2 OR 4. THE NEXT FACTOR THAT
C IPREV MUST TAKE. AND IREM = N/(IFACT*IPREV). THEN--
C DIMENSION DATA(NPREV•IPREV•IFACT•IREM•NRFM)
C COMPLEX DATA
C DATA(J1•J2•K3•J4•J5) = SUM(DATA(J1•J2•J3•J4•J5)*EXP((ISIGN*2*PI*I*
C (K3-1)*((J3-1)/IFACT+(J2-1)/(IFACT*IPREV)))) * SUMMED OVER J3 = 1
C TO IFACT FOR ALL J1 FROM 1 TO NPREV. J2 FROM 1 TO IPREV. K3 FROM
C 1 TO IFACT. J4 FROM 1 TO IREM AND J5 FROM 1 TO NREM. THIS IS
C A PHASE-SHIFTED DISCHETE FOURIER TRANSFORM OF LENGTH IFACT.
C FACTORING N BY FOURS SAVES ABOUT TWENTY FIVE PERCENT OVER FACTOR-
C ING BY TWOS. DATA MUST BE HIT-REVERSED INITIALLY.
C IT IS NOT NECESSARY TO REWRITE THIS SUBROUTINE INTO COMPLEX
C NOTATION SO LONG AS THE FORTRAN COMPILER USED STORES REAL AND
C IMAGINARY PARTS IN ADJACENT STORAGE LOCATIONS. IT MUST ALSO
C STORE ARRAYS WITH THE FIRST SUBSCRIPT INDEX ASING FASTEST.
C DIMENSION DATA(1)
C TWOPT=6.281853072*FLOAT(ISIGN)
C02 1
IP0=2
C02 2
IP1=IP0*NPREV
C02 3
IP4=IP1*N
C02 4
IP5=IP4*NRFM
C02 5
IP2=IP1
C02 6
IP2=IP1*IPRN
C02 7
NPART=N
C02 8
IF (NPART-2) 60•30•20
C02 9
NPART=NPART/4
C02 10
GO TO 10
C02 11
DC A FOURIER TRANSFORM OF LENGTH TWO
C02 12
IF ((IP2-IP4) 40.160•160
C02 13
IP3=IP2*2
C02 14
C02 15
C02 16
C02 17
C02 18
C02 19
C02 20
C02 21
C02 22
C02 23
C02 24
C02 25
C02 26
C02 27
C02 28
C02 29
C02 30
C02 31
C02 32
C02 33
C02 34
C02 35
C02 36
C02 37
C02 38
C02 39
C02 40

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C      IP3=IP2*IFACT          41
C      DO 50 I1=1*IP1*IP0      C02 42
C      I1 = 1+(J1-1)*IP0      C02 43
C      DO 50 I5=I1*IP5*IP3    C02 44
C      I5 = 1+(J1-1)*IP0+(J4-1)*IP3+(J5-1)*IP4   C02 45
C      I3A=I5                  C02 46
C      I3B=I3A+IP2             C02 47
C      I3 = 1+(J1-1)*IP0+(J2-1)*IP1+(J3-1)*IP2+(J4-1)*IP3+(J5-1)*IP4   C02 48
C      TEMP0=DATA(I3H)         C02 49
C      TEMP1=DATA(I3H+1)       C02 50
C      DATA(I3R)=DATA(I3A)-TEMP0
C      DATA(I3R+1)=DATA(I3A+1)-TEMP1   C02 51
C      DATA(I3A)=DATA(I3A)+TEMP0
C      DATA(I3A+1)=DATA(I3A+1)+TEMP1   C02 52
C      IP2=IP3                 C02 53
C      DO A FOURIER TRANSFORM OF LENGTH FOUR (FROM HIT REVERSED ORDER)   C02 54
C      IF (IP2-IP4) 70.160.160   C02 55
C      IP3=IP2*4                C02 56
C      IP3=IP2*IFACT            C02 57
C      THETA=TWOPI/FLOAT(IP3/IP1)
C      SINTH=SIN(THETA/2.)
C      WSTPR=-2.*SINTH*SINTH
C      COS(THETA)-1. FOR ACCURACY.
C      WSTPI=SIN(THETA)
C      WH=1.

WI=0.
DO 150 I2=1*IP2*IP1          60
C      I2 = 1+(J2-1)*IP1
C      IF (I2-1) 90.90.80        C02 61
C      W2R=WR*WR-WI*WI
C      W2I=2.*WP*WI
C      W3R=W2R*WR-W2I*WI
C      W3I=W2R*WI+W2I*WR
C      I1MAX=I2+IP1-IP0
DO 140 I1=I2*I1MAX*IP0        70
C      I1 = 1+(J1-1)*IP0+(J2-1)*IP1
DO 140 I5=I1*IP5*IP3          80
C      I5 = 1+(J1-1)*IP0+(J2-1)*IP1+(J4-1)*IP3+(J5-1)*IP4
C      I3A=I5
C      I3R=I3A+IP2
C      I3C=I3R+IP2
C      I3D=I3C+IP2
C      I3 = 1+(J1-1)*IP0+(J2-1)*IP1+(J3-1)*IP2+(J4-1)*IP3+(J5-1)*IP4
C      IF (I2-1) 110.110.100
C      APPLY THF PHASE SHIFT FACTORS
C      TEMP0=DATA(I3H)
C      TEMP0=W2R*DATA(I3H)-WI*DATA(I3H+1)
C      DATA(I3H+1)=W2R*DATA(I3H+1)+W2I*TEMP0
C      TEMP0=DATA(I3C)
C      DATA(I3C)=WH*DATA(I3C)-WI*DATA(I3C+1)
C      DATA(I3C+1)=WH*DATA(I3C+1)+WI*TEMP0
C      100

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TTEMPR=DATA(I3D)
DATA(I3D)=W3P*DATA(I3D)-W3I*DATA(I3D+1)
DATA(I3D+1)=W3P*DATA(I3D+1)+W3I*TEMPPR
110   T0R=DATA(I3A)+DATA(I3H)
      T0I=DATA(I3A+1)+DATA(I3H+1)
      T1R=DATA(I3A)-DATA(I3H)
      T1I=DATA(I3A+1)-DATA(I3H+1)
      T2R=DATA(I3C)+DATA(I3D)
      T2I=DATA(I3C+1)+DATA(I3D+1)
      T3R=DATA(I3C)-DATA(I3D)
      T3I=DATA(I3C+1)-DATA(I3D+1)
      DATA(I3A)=T0P+T2R
      DATA(I3A+1)=T0I+T2I
      DATA(I3C)=T0R-T2R
      DATA(I3C+1)=T0I-T2I
      IF (ISIGN) 120,120,130
120   T3R=-T3P
      T3I=-T3I
130   DATA(I3R)=T1R-T3I
      DATA(I3R+1)=T1I+T3H
      DATA(I3D)=T1R+T3I
      DATA(I3D+1)=T1I-T3H
140   TEMP=WP
      W=WSTPR*TEMPPR-WSTPI*TFMPR+WI
150   WI=WSTPR*WI+WSTPI*TFMPR+WI
      IP2=IP3
      GO TO 60
160   RETURN
      END
      #

```

PROGRAM CHECK(INPUT,OUTPUT,TAPES=INPUT,TAPE6=OUTPUT)

THIS PROGRAM WAS WRITTEN BY R. AKINS COLORADO STATE UNIVERSITY TO ILLUSTRATE THE USE OF SUBROUTINE FOURT. FORWARD AND INVERSE TRANSFORMS OF A KNOWN FUNCTION ARE PERFORMED AND THE RESULTS ARE COMPARED WITH THE EXACT VALUES.

PROGRAM VARIABLES IN ALPHABETICAL ORDER ARE--

```

10      D - ARRAY USED AS INPUT AND OUTPUT FROM SUBROUTINE FOURT
      DELTAT - TIME STEP OF INPUT FUNCTION
      DELTAW - FREQUENCY STEP CORRESPONDING TO DELTAT
      FREQ - ACTUAL FREQUENCY AT A GIVEN ELEMENT OF D
      NUMBER - NUMBER OF DATA POINTS USED IN TRANSFORMS
      NUMBER2 - NUMBER OF DATA POINTS AFTER REFLECTION USED IN TRANSFORMS
      TIME - ACTUAL TIME AT A GIVEN ELEMENT OF D
      DIMENSION D(2,4096)

      READ INPUT VARIABLES

20      3 READ(5,111)NUMBER,DELTAT
      1 IF.EOF(5).300.5
      5 NUMBER2=NUMBER*2
      DELTAW=6.2832/(DELTAT*FLOAT(NUMBER2))
      COMPUTE INPUT EXPONENTIAL FUNCTION - STORE IT IN D(1,I) CORRESPONDING
      TO THE REAL PART OF THE FOURT INPUT. PLACE A ZERO IN D(2,I)
      CORRESPONDING TO THE IMAGINARY PART OF FOURT INPUT.

30      DO 10 I=1,NUMBER
      D(1,I)=EXP(-FLOAT(I-1)*DELTAT)
      D(2,I)=0.0
      10 C REFLECT THE INPUT FUNCTION

35      D(1,NUMBER+1)=D(1,NUMBER)
      DO 20 I=2,NUMBER
      K=NUMBER-I+2
      L=NUMBER+I
      D(2,L)=0.0
      D(2,I)=D(1,K)
      20 C PERFORM A FORWARD(-1) TRANSFORM ON THE DATA
      CALL FOURT(D,NUMBER2,1,-1,0,0)

40      C COMPUTE ACTUAL TRANSFORM AND PRINT OUT A COMPARISON WITH THE OUTPUT
      OF SUBROUTINE FOURT

45      CPTIME=SECOND(A)
      WRITE(6,201)NUMBER,DELTAT,CPTIME
      WRITE(6,115)
      DO 30 I=1,NUMBER
      D(1,I)=D(1,I)*DELTAT*2.0
      DO 35 I=1,NUMBER,10
      ACTUAL=4.0/((1.0/(FLOAT(I-1)*DELTAW))*2)
      FREQ=FLOAT(I-1)*DELTAW
      WRITE(6,120)FREQ,D(1,I),ACTUAL
      35 D(2,I)=0
      D(2,NUMBER+1)=0

```

```

60      D(1,NUMBER+1)=D(1,NUMBER)
DO 40   I=2,NUMBER
K=NUMBER-I+2
L=NUMBER+I
D(2,L)=0.0
D(2,I)=0.0
D(1,L)=0.0
40      D(1,I)=D(1,K)

C      C      PERFORM AN INVERSE (+1) TRANSFORM OF THE DATA
C      C      CALL FOURT(D,NUMBER2,1,1,0,0)

70      C      C      COMPARE THE RESULTS OF A FORWARD AND INVERSE TRANSFORM WITH
C      C      THE ORIGINAL DATA

75      CPTIME=SECOND(A)
      WRITE(6,201)NUMBER,DELTAT,CPTIME
      WRITE(6,110)
      VALUE=D(1,1)
      DO 60 I=1,NUMBER+10
      TIME=FLOAT(I-1)*DELTAT
      D(2,I)=EXP(-TIME)
      D(1,I)=D(1,I)/(FLOAT(NUMBER)*DELTAT*4)
60      WRITE(6,120)TIME*D(1,I)*D(2,I)
      110 FORMAT(11X,*T(SEC)      COMPUTED R(T)      ACTUAL R(T)*)
      111 FORMAT(110*F10.3)        COMPUTED F(W)      ACTUAL F(W)*)
      115 FORMAT(11X,*W(RPS)      COMPUTED F(W)
      120 FORMAT(10X,F7.3*2E14.5)
      201 FORMAT(10X,*N=*,14.5X,*DELTAT = *,F6.3,5X,*CPTIME = *,F8.5)
      90      GO TO 3
      300 CONTINUE
      END

```

PROGRAM SFGEMLNT (INPUT, OUTPUT, TAPES=INPUT, TAPE6=OUTPUT, TAPE1)

THIS PROGRAM WAS WRITTEN 8/75 BY R. AKINS CSU TO COMPUTE POWER SPECTRAL DENSITIES (PSD) FROM A TIME SERIES USING SUBROUTINE FOURT. AN INVERSE TRANSFORM OF THE PSD AND OBTAIN AN AUTOCORRELATION (ACR) FUNCTION PLOTS OF BOTH THE PSD AND THE ACR WILL BE MADE USING THE U200 HARD COPY PLOTTER

5

SUBROUTINES CALLED ARE ALL PLOT SUBROUTINES AND DESCRIBED IN THE CSU USERS MANUAL 1975 EDITION

AXIS - PLOT ROUTINE  
CURVE - PLOT ROUTINE  
FPNAME - PLOT ROUTINE  
FIRSTPFT - PLOT ROUTINE  
FOURT - FFT SUBROUTINE CALLED FROM FTNLIN  
IPS - SUBROUTINE TO INTEGRATE THE SPECTRA  
LOCAT - PLOT ROUTINE  
MACROT - CALCULATES INTEGRAL TIME SCALES FOR THE ACR  
MICP01 - CALCULATES MICROSCALE FROM  $(N^{**}2)*F(N)$   
MICP02 - CALCULATES MICROSCALE FROM ACR  
PFT - PLOT ROUTINE  
RFADATA - READS DATA RECORD FORM TAPE1 (12 BIT WORDS)  
SFT - PLOT ROUTINE  
SYMBOL - PLOT ROUTINE  
UNPAK2 - CONVERTS DATA RECORD FROM 12 TO 60 BIT WORDS  
VFCCT2 - PLOT ROUTINE

INPUT VARIABLES IN ALPHABETICAL ORDER ARE

GAIN - GAIN OF LINEAR TRANSDUCER  
IC04 - CODE FOR CORRELATION CALCULATION  
IPATF - SAMPLE RATE OF DATA  
IPEC - RECORD LENGTH OF TAPE1 (DATA TAPE)  
KFY1-5 - PLOT LABELS FOR BOTH PSD AND ACR PLOT  
LARY - X AXIS LABEL FOR PSD  
LAHY - Y AXIS LABEL FOR PSD  
NSEGM - NUMBER OF SEGMENTS TO AVERAGE  
TITLE - ALPHANUMERIC ARRAY USED TO LABEL PRINTED OUTPUT  
XTIT - X AXIS LABEL FOR CORRELATION PLOT  
YTIT - Y AXIS LABEL FOR CORRELATION PLOT

PROGRAM VARIABLES

A - ARRAY OF 12 BIT WORDS READ FROM TAPE INPUT TO UNPACK  
B - ARRAY OF 20 BIT WORDS OUTPUT FROM UNPACK  
CONST - NORMALIZING FACTOR FOR ACR  
D - 2 DIMENSIONAL ARRAY USED TO SIMULATE COMPLEX NUMBERS  
DFLTAN - FREQUENCY INTERVAL OF SPECTRA  
DFLTAT - TIME STEP OF INPUT DATA  
FACTOR - CONSTANT USED IN SPECTRA CALCULATIONS  
IND - INDEX USED IN SETTING UP PLOT ARRAYS  
KTAPER - UPPER LIMIT TAPER START  
LTAPER - LOWER LIMIT TAPER CUTOFF  
NFW - NUMBER/2  
NPLOT - PLOT PARAMETER  
NFEC - NUMBER OF RECORDS TO BE READ FROM THE TAPE PER SEGMENT

60 CCCCCCCCCC  
 RMS - LENGTH OF ARRAY  
 SFMEN - COMPUTED VALUE OF RMS  
 TOTAL - STORE THE SEGMENT AVERAGED SPECTRA  
 UTAPER - FLOATING POINT VERSION OF NUMBER  
 TAPER - TAPE R FACTOR  
 X - INPUT ARRAY FOR PLOTS  
 XMAN - RUNNING TOTAL USED IN MEAN CALCULATIONS  
 X2 - RUNNING TOTAL USED IN RMS CALCULATIONS  
 Y - INPUT ARRAY FOR PLOTS

65 COMMON D(2\*192)\*N,SEGMENT(4096)  
 DIMENSION X(500)\*Y(500)\*TITLE(8)  
 DIMENSION XTIT(4)\*YTIT(4)\*LABX(4)\*LABY(4)  
 DIMENSION KEY1(3)\*KEY2(3)\*KEY3(3)\*KEY4(3)\*KEY5(3)\*KEY6(3)

70 COMMON /INPK/A(204)H(1020)  
 COMMON /1/IREC,IPATE,K1  
 DATA Y/500\*0/0/  
 DO 1 J=1,4096  
 1 SEGMENT(J)=0.0  
 NUMREP=192

75 CCCCCCCCC  
 IN ORDER TO CHANGE THE SIZE OF ARRAY D, TWO CARDS NEED TO BE  
 CHANGED, THE DIMENSION CARD AND THE VALUE OF NUMBER

80 CCCCCCCCC  
 READ THE INPUT VARIABLES

85 READ(S,SOL)TITLE  
 501 FORMAT(4A10)  
 READ(S,500)NSEGM,IRFC,IRATE,ICOR,GAIN

90 500 FORMAT(4I10\*F10.3)  
 READ(S,510)XTIT  
 READ(S,510)YTIT  
 READ(S,510)LABX  
 READ(S,510)LABY  
 READ(S,511)KEY1  
 READ(S,511)KEY2  
 READ(S,511)KEY3  
 READ(S,511)KEY4  
 READ(S,511)KEY5  
 READ(S,511)KEY6  
 510 FORMAT(4A10)  
 511 FORMAT(3A10)  
 CALL LOCAT(28AT)  
 CALL PENZ(5HBLCK,4HFLT)

100 CCCCC  
 READ INPUT DATA OR TAPE1, COMPUTE THE MEAN AND THE RMS

105 CCCCC  
 WRITE(5,600)TITLE,NSEGMENT,NUMBER,IREC,IRATE  
 NPFCE=NPFER/IREC+1  
 DO 100 K=1,NSEGM  
 ICOUNT=1  
 XMFAN=0.0  
 X2=0.0

110 600 FORMAT(1H1,8A10//5X\*A,SEGMENT,1  
 1 USING 14\* SFMEN\*/\*5X\*OF LENGTH \*16\*  
 2 RECORDS \*15\* VALUES LONG AT A SAMPLE\*/5X\*RATE OF \*16\* SPS.  
 3\*/\*11X\*SEGMENT\*17X\*XMFAN\*,16X,RMS\*)  
 DO 10 K=1,IREC

```

CALL PFANATA
CALL UNPKW2(A•••I••C)
DO K J=1,IREC
  R(J)=A(J)*GAIN
  D(1•ICOUNT)=R(J)
  D(2•ICOUNT)=0.0
  XMEAN=XMEAN+R(J)
  X2=X2+B(J)**2
  IF(ICOUNT>COUNT)GO TO 12
  ICOUNT=ICOUNT+1
  10 CONTINUE
  12 TOTAL=FLOAT(COUNT)
  XMFAN=XMEAN/TOTAL
  PWSQRT(XMS*(X2-XMFAN*XMFAN*TOTAL)/TOTAL)
  WRITE(6•601)K,XMEAN,RMS
  601 FORMAT(13x,14.15x,F10.7,F10.7)
C
C      TAPE AND NORMALIZE THE DATA ( REMOVE MEAN, DIVIDE BY RMS)
C
  LTAPER=NUMBER/10
  KTAPER=NUMBER-LTAPER
  DO 135 I=1,NUMBER
    D(I,I)=(I-1)-XMEAN)/RMS
    IF(I>LTAPER)GO TO 13
    FRAC=FLOAT(I-1)/FLOAT(LTAPER-1)
    UTAPER=COS(1.570796*(1-FRAC))**2
    D(I,I)=D(I,I)*UTAPER
    GO TO 15
  13 IF(I>LTAPER)GO TO 15
    KK=(LTAPER-1)-(I-LTAPER)
    FRAC=FLOAT(KK)/FLOAT(LTAPER-1)
    UTAPER=COS(1.570796*(1.0-FRAC))**2
    D(I,I)=D(I,I)*UTAPER
    15 CONTINUE
C
C      PERFORM A FORWARD TRANSFORM OF THE DATA ARRAY D
  140 CALL FOHFT(D•NUMBER•1•-1•0•0)
  NF=NUMBER/
  DELTAT=1.0/FLOAT(DLTAT)
  FACTOR=2.0*1.143*(DLTAT)/TOTAL
  DELTAN=1.0/(TOTAL*DLTAT)
C
C      AND THE INCREMENT INTO ARRAY SEGMENT. THE SEGMENT AVERAGED SPECTRA
  145
  150
  155
  160
  165
  170
  175
C
C      COMPUTE THE CORRELATION FUNCTION FROM THE N SEGMENT AVERAGED SPECTRA
C
N=NUMBER/2
C
C      REFLECT THE STRUCTURE INTO THE D ARRAY
C
  DO 110 I=1,N
    D(I,I)=SEGMENT(I)+FACTOR*(D(I,I)**2*D(2,I)**2)/FLOAT
    D(2,I)=0.0
    110 CONTINUE

```

```

D(1+N+1)=D(1+N)
D(2+N+1)=0.0
DO 115 I=2,N
K=N-1+2
L=N+1
D(I,L)=0.0
D(I+L)=D(I,K)

```

180

```

C      PERFORM AN INVERSE TRANSFORM TO OBTAIN A CORRELATION FUNCTION
C      CALL FOURI(D,NUMLER,1.1,0.0)

```

185

C NORMALIZE THE CORRELATION FUNCTION

190

```

CONST=D(1,1)
DO 120 I=1,N
  D(I,I)=D(I,I)/CONST
C      PLACE THE NORMALIZED CORRELATION FUNCTION INTO ARRAY Y AND
C      GENERATE ARRAY X - TIME STEPS
C      DO 130 I=1,50
X(I)=FLOAT(I-1)*DELTAT
Y(I)=R(I,1)
IND=51
DO 135 I=60,N,10
Y(IND)=D(I,1)
X(IND)=FLOAT(I-1)*DELTAT
IF(X(IND).GT.1.0)GO TO 137
IND=IND+1
137 NPLOT=IND

```

195

```

C      OUTPUT AND PLOT THE CORRELATION FUNCTION
C      WRITE(6,602)TITLE
DO 140 I=1,NPLOT,5

```

200

```

140  WRITE(6,603)X(I),Y(I),X(I+1)*Y(I+1)*X(I+2)*Y(I+3)*X(I+4)*Y(I+5)
  602 FORMAT(1H1,HA10,/,10X,*AUTOCORRELATION FUNCTION*,//,5(* TIME
  1   RT)/*/*)
  603 FORMAT(10F10.6)
CALL SET(1.05,0.1,0.6,0,0,0,1,0,-2,1,0,1,1)
CALL AXIS(0,0,0,YTITLE,4,0,6,90,0,-2,2,1)
CALL AXIS(0,0,0,XTITLE,4,0,5,0,0,0,0,0,2,1)
CALL SYMBOL(2,0,4,6,2,KEY1,1,0,0,3,0)
CALL SYMBOL(2,0,4,3,2,KEY2,2,0,0,3,0)
CALL SYMBOL(2,0,4,0,2,KEY3,3,0,0,3,0)
CALL SYMBOL(2,0,3,7,2,KEY4,4,0,0,3,0)
CALL SYMBOL(2,0,3,4,2,KEY5,5,0,0,3,0)
CALL SYMBOL(2,0,3,1,2,KEY6,6,0,0,3,0)
CALL FIRSTP(0,0,0,0)
CALL VECTOR(1,0,0,0)
NPLOT=NPLOT-1
CALL CURVE(X,Y,NPLOT,0,2)
CALL FWF
DO 153 I=1,500

```

205

210

```

215
C      WRITE(6,602)TITLE
DO 140 I=1,NPLOT,5
  140  WRITE(6,603)X(I),Y(I),X(I+1)*Y(I+1)*X(I+2)*Y(I+3)*X(I+4)*Y(I+5)
  602 FORMAT(1H1,HA10,/,10X,*AUTOCORRELATION FUNCTION*,//,5(* TIME
  1   RT)/*/*)
  603 FORMAT(10F10.6)
CALL SET(1.05,0.1,0.6,0,0,0,1,0,-2,1,0,1,1)
CALL AXIS(0,0,0,YTITLE,4,0,6,90,0,-2,2,1)
CALL AXIS(0,0,0,XTITLE,4,0,5,0,0,0,0,2,1)
CALL SYMBOL(2,0,4,6,2,KEY1,1,0,0,3,0)
CALL SYMBOL(2,0,4,3,2,KEY2,2,0,0,3,0)
CALL SYMBOL(2,0,4,0,2,KEY3,3,0,0,3,0)
CALL SYMBOL(2,0,3,7,2,KEY4,4,0,0,3,0)
CALL SYMBOL(2,0,3,4,2,KEY5,5,0,0,3,0)
CALL SYMBOL(2,0,3,1,2,KEY6,6,0,0,3,0)
CALL FIRSTP(0,0,0,0)
CALL VECTOR(1,0,0,0)
NPLOT=NPLOT-1
CALL CURVE(X,Y,NPLOT,0,2)
CALL FWF
DO 153 I=1,500

```

220

225

230

235

C PLACE THE FIRST 10 POINTS OF THE SPECTRA INTO ARRAY Y AND ASSOCIATED

```

C   FREQUENCY INT(0 X
240   DO 150 I=1*10
      X(I)=FLOAT(I)*DELTAN
      IND=11
      IND=IND+1
C   FREQUENCY AVERAGE 3 POINTS
245   DO 154 I=11*50*3
      DO 157 J=1*3
      Y(IND)=Y(IND)+SEGMENT(I+J-1)
      Y(IND)=Y(IND)/3.0
      X(IND)=FLOAT(I+1)*DELTAN
      IND=IND+1
      N2=N-10
C   FREQUENCY AVERAGE 10 POINTS
250   DO 155 I=60*N2*10
      DO 156 J=1*10
      Y(IND)=Y(IND)+SEGMENT(I+J-1)
      X(IND)=FLOAT(I+5-1)*DELTAN
      Y(IND)=Y(IND)/10.0
      IND=IND+1
      NPLOT=IND-1
      WRITE(6*607) SEGMENT(I)
      607 FORMAT(1H0*10X*THT FIRST ELEMENT OF SEGMENT IS *.*E15.4)
      WRITE(6*604) TITLE
      DO 160 I=1*4
      PLUT(I)=Y(I)
      160 WRITE(6*605) X(I)*Y(I)*X(I+1)*Y(I+1)*X(I+2)*Y(I+3)
      604 FORMAT(1H1*HALU./>1HX.*NORMALIZF) POWER SPECTRAL DENSITY FUNCTION*
      1*/*-*(* F(FU-CPS F(N))*)*//)
      605 FORMAT(1H15.7)
      CALL LBS(SEGMEN*DELTAN*SUM*N)
      WRITE(6*606) SUM
      608 FORMAT(1H0*10X*ARFA OF SEGMENT = *.*F10.5)
      CALL SFT(1*5*925*1.75*12*45*0.0*0.000001*1.0*2*7*4)
      CALL PERIM(5*0*7*0)
      CALL SYMBOL(3*5*7*8*25*LAM*0*0*40)
      CALL SYMBOL(-5*3*0*25*LAM*90*0*40)
      CALL SYMBOL(1*0*3*5*2*KEY1*0*0*30)
      CALL SYMBOL(1*0*3*2*2*KEY2*0*0*30)
      CALL SYMBOL(1*0*2*9*2*KEY3*0*0*30)
      CALL SYMBOL(1*0*2*6*2*KEY4*0*0*30)
      CALL SYMBOL(1*0*2*3*2*KEY5*0*0*30)
      CALL CUPVE(1*0*2*0*2*KEY6*0*0*30)
      CALL FRAFF
      CALL MACROT(DELTAT)
      CALL MICRO2(DELTAT)
      CALL MICRO1(DELTAN*MICR01)
      280   WRITE(6*606) MICR01
      606 FORMAT(1H0*1UX.*MICROSCALE COMPUTED BY INTEGRATING N2F(N)*.*F10.6)
      END

```

PROGRAM EXTCORE (INPUT,OUTPUT,TAPES=INPUT,TAPE6=OUTPUT,TAPE1,TAPE2,  
ITAPE3)

5

THIS PROGRAM WAS WRITTEN BY W. AKINS TO COMPUTE A POWER SPECTRAL  
USING SUBROUTINE FOR2, AN EXTERNAL CORE FFT ROUTINE  
SUBROUTINES CALLED IN ALPHABETICAL ORDER ARE  
ALL PLOT ROUTINES ARE DISCUSSED IN THE CSU USERS MANUAL

10 CURVE - PLOT ROUTINE  
DHEAD - READS RECORDS FROM MASS STORAGE  
DWHIT - WRITES ON MASS STORAGE, REWRITING OVER OLD DATA USED AFTER THE  
DATA HAS BEEN WRITTEN ONCE  
DWRITI - WRITES ON MASS STORAGE - FIRST TIME  
FOR2D - EXTERNAL CORE FFT  
FPLATE - PLOT ROUTINE  
IDS - INTEGRATION SUBROUTINE  
LOCAT - PLOT ROUTINE  
PENZ - PLOT ROUTINE  
PERIM - PLOT ROUTINE  
OPENMS - SETS UP MASS STORAGE - SYSTEM SUBROUTINE  
RFADATA - READS 1 DATA RECORD IREC VALUES LONG FROM TAPE1 USING ARRAY  
SYMBOL - PLOT ROUTINE  
UNPAK2 - CHANGES FROM 12 HIT TO 60 BIT WORDS  
25 TAPF UNITS USED -

30 TAPF 1 - DATA TAPE  
TAPF 2 - MASS STORAGE  
TAPF 3 - OUTPUT FOR EQUALLY AVERAGED SPECTRA  
TAPF 5 - CARD INPUT  
TAPF 6 - PRINTED OUTPUT  
A - ARRAY OF 12 HIT WORDS INPUT TO UNPACK, READ FROM TAPE1  
B - ARRAY OF 60 HIT WORDS OUTPUT FROM UNPACK  
DFLATN - FREQUENCY STEP FOR GIVEN AVERAGING INTERVAL  
DFLTTAT - TIME STEP OF DATA \* 1/RATE  
FACTOR - FACTOR TO MULTIPLY OUTPUT OF FOR2D  
FREQ - REAL ARRAY USED TO STORE THE FREQUENCY VALUES FOR SPECT  
GAIN - CALIBRATION FACTOR  
ICHAN - CHANNEL TO BE USED  
ICOUNT - COUNTER USED IN TAPERING. AND IN INITIALLY PLACING THE DATA  
INIFIX - INTEGER ARRAY USED IN MASS STORAGE CONTROL  
INDFX1 - COUNTDOWN USED TO KEEP TRACK OF MASS STORAGE LOCATIONS ON INPUT  
IRATE - SAMPLE RATE PER CHANNEL TAPE1  
IREC - NUMBER OF DATA VALUES PER DATA RECORD, TAPE1  
ISP - COUNTDOWN USED IN FREQUENCY SMOOTHING  
KFY 1 - TITLE CARD FOR PLOT OF SPECTRUM  
KFY 2 - TITLE CARD FOR PLOT OF SPECTRUM  
KFY 3 - TITLE CARD FOR PLOT OF SPECTRUM  
KFY 4 - TITLE CARD FOR PLOT OF SPECTRUM  
KFY 5 - TITLE CARD FOR PLOT OF SPECTRUM  
KFY 6 - TITLE CARD FOR PLOT OF SPECTRUM  
KTAPER - USED IN TAPERING THE DATA  
LAX - PLOT AXIS LABEL  
LARY - PLOT AXIS LABEL  
LIMIT(1,1) - NUMBER OF POINTS TO AVERAGE 1TH INTERVAL  
LIMIT(2,1) - NUMBER OF RAW POINTS 1-TH INTERVAL  
LIMIT(3,1) - NUMBER OF AVERAGED POINTS 1-TH INTERVAL

```

60      LTAPER - USED IN TAPERING THE DATA DIMENSION OF ENTIRE DATA ARRAY INPUT TO FOR2D
       NAVG - ARRAY GIVING NUMBER OF AVERAGING INTERVALS
       NAVG1 - UNIFORM AVERAGING TO BE USED IN OUTPUT TO TAPE 1
       NCHAN - NUMBER OF CHANNELS OF DATA ON TAPE 1
       NREC - COUNTER USED IN INTEGRATION
       NRECUD - TOTAL NUMBER OF RECORDS NEEDED TO READ N(1) VALUES FROM TAPE 1
       NTRFC - NUMBER OF RECORDS NEEDED TO READ N(1) VALUES FROM TAPE 1
       NUMREC - LENGTH OF DATA RECORDS IN MASS STORAGE +1
       N1 - NUMBER OF RECORDS TO BE USED IN MASS STORAGE +1
       PFUNC(X) - GAIN*X - CALIBRATION FOR A LINEAR TRANSDUCER
       PKH1 - HIGHEST VALUE OF RECORD
       PKLO - SMALLEST VALUE OF RECORD
       RMS - ROOT-MEAN-SQUARE OF THE INPUT DATA
       RMS2 - RMS**2

65      SPECT - REAL ARRAY USED TO STORE THE SMOOTHED SPECTRUM
       SC - SUM OF SQUARES OF DATA VALUES
       STUFF - REAL ARRAY USED IN UNIFORM SMOOTHING OF THE SPECTRUM
       TFMP - COMPLEX ARRAY NUMBER ELEMENTS LONG, USED WITH FFT
       TOTAL - TOTAL NUMBER OF POINTS USED IN THE FFT

70      UTAPER - USED IN TAPERING THE DATA
       WORK - COMPLEX ARRAY 3*NUMBER ELEMENTS LONG USED WITH FOR2D AND MASS S
       STOPAGE - READ AND WRITE ROUTINES
       XINC - ARRAY USED IN INTEGRATION TO STORE FREQUENCY INCREMENTS
       XINT - RUNNING VALUE OF INTEGRAL OF SPECTRA
       XILIMIT(1,I) - HANDWRITEN FOR THE I-TH AVERAGING INTERVAL
       XILIMIT(2,I) - UPPER LIMIT FOR THE I-TH AVERAGING INTERVAL
       XMEAN - RUNNING MEAN

75      COMPLEX TEMP
       COMPLEX WORK
       COMMON/UNDK/A(204)*H(1020)
       COMMON/1/IREC,NCHAN,IRATE
       COMMON/2/IRUN,DIAM,LEN2,IND1,IND2
       DIMENSION WORK(3072)*N(3)*INDEX(513),SPECT(1200),FREQ(2000)
       DIMENSION STORE(12)
       DIMENSION LAHX(4)*LAHY(4)*KEY1(3)*KEY2(3)*KEY3(3)*KEY4(3)*KEY5(3),
       1KEY6(3)
       DIMENSION XLIMIT(2*6)*LIMIT(3*6)
       DIMENSION XINC(6)
       DATA SPECT/1200*0./
       DATA STORE/8*0.*0./
       PFUNC(X)=GAIN*X

80      C C HFAN IN PARAMETERS FOR PROGRAM EXECUTION

85      C C

90      XINT=0.0
       CALL PEND(5MBLACK+4HFFLT)
       GAIN = 04114
       READ(5,1000)IREC,NCHAN,IRATE,N(1),NAVG,NRECORD,NUMBER,N1
       FORMAT(410)
       READ(5,1001)LAHX
       READ(5,1001)LAHY
       READ(5,1002)KEY1
       READ(5,1002)KEY2
       READ(5,1002)KEY3
       READ(5,1002)KEY4

95      1000
       READ(5,1000)LAHX
       READ(5,1001)LAHY
       READ(5,1002)KEY1
       READ(5,1002)KEY2
       READ(5,1002)KEY3
       READ(5,1002)KEY4

```

```

120      READ(5,1002)KEY5
        READ(5,1002)KEY6
1001      FORMAT(4A10)
1002      FORMAT(3A10)
        READ(5,1003)(LIMIT(1,J),J=1,NAVG)
        READ(5,1003)(LIMIT(2,J),J=1,NAVG)
1003      FORMAT(6I10)

C      OPEN MASS STORAGE
C
C      CALL OPFNMS(2,INDEX,N1,0)
130      N1=N1-1
        NTRFC=N(1)*NCHAN/IHFC+1
        IF(NTRFC.GT.NRECORD)STOP11

C      INITIALIZE PROGRAM PARAMETERS
C
C      XMFFAN=0.0
        PKHI=-100.0
        PKLO=100.0
        SQ=0.0
        ICOUNT=0
        INDEX1=1
        ICHAN=ICHAN-1
DO 10 I=1,NTREC
140
C      READ THE DATA OFF OF TAPE1, UNPACK IT FORM 12 TO 60 BIT WORDS
C
C      CALL PEADATA
        CALL INPAK2(A,H,IHFC)
DO 5 J=1,IREC,NCHAN
        J=J+ICHAN
        R(J)=P FUNC(R(J))
        XMFFAN=XMFAN+B(J)
        S0=S0+H(J)*B(J)
        IF(R(J).LT.PKHI)GO TO 3
        PKHI=P(J)
        3 IF(R(J).GT.PKLO)GO TO 5
        5 CONTINUE
C
C      PLACE THE DATA INTO MASS STORAGE 1 RECORD NUMBER DATA VALUES LONG
AT A TIME
C
DO 10 J=1,IREC,NCHAN
        J=J+ICHAN
        ICOUNT=ICOUNT+1
        WORK(ICOUNT)=R(J)
        IF(ICOUNT*NE.NUMBER) GO TO 10
        ICOUNT=0
        CALL DWRITE(2,INDEX1,WORK,1,NUMBER)
        INDEX1=INDEX1+1
10 CONTINUE

C      COMPUTE THE MEAN AND THE RMS
C
C      TOTAL=FLOAT(NTREC)*FLOAT(IHFC)/FLOAT(NCHAN)
        XMEAN=XMFAN/TOTAL
        RMS=SQ((S0-XMFAN*XMFAN)/TOTAL)
175

```

```

      WRITE(6,2000)IREC,IHATE,N1,NUMBFX,RMS,PKHI,PKLO
      2000 FORMAT(1I1),10X,*TRIAL RUN OF FOR2D FOR PRESSURE SPECTRA*//,10X,*R
      1F00D LENGTH = * *17* SAMPLE RATE = * *17* SAMPLES/SECOND*//,10X,*
      2FOR2D WAS CALLED USING*15* RECORDS OF LENGTH*,17*,10X,*RECORDS = * *17* SAMPLES OF LENGTH*,17*,10X,*R
      4MEAN = * *F10.6*20X,* (ALL UNITS PSI)* * /10X,*RMS = * *F10.6* //,10X,*R
      SPEAK HIGH = * *F10.6/*10X,*PEAK LOW = * *F10.6)

      C      HFCALL THE DATA*REMOVE THE MEAN,TAPER IF APPROPRIATE *RETURN TO STORAGE
      C      LTAPER=N(1)/10
      C      KTAPER=N(1)-LTAPER
      ICOUNT=1
      DO 20 J=1,N1
      CALL FREAD(2,J,WORK,1,NUMBER)
      DO 15 K=1,NUMBER
      WORK(K)=WORK(K)-XMEAN
      1F (ICOUNT.GT.LTAPER) GO TO 1?
      FRAC=FLOAT(ICOUNT-1)/FLOAT(LTAPER-1)
      UTAPER=COS((1.570796*(1.0-FRAC))**2)
      12 WORK(K)=WORK(K)*UTAPER
      IF (ICOUNT.LT.KTAPER) GO TO 14
      KK=(LTAPER-1)-(ICOUNT-KTAPER)
      FRAC=FLOAT((KK)/FLOAT(LTAPER-1))
      UTAPER=COS((1.570796*(1.0-FRAC))**2)
      WORK(K)=WORK(K)*UTAPER
      14 ICOUNT=ICOUNT+1
      15 CONTINUE
      20 CALL DWRITE(2,J,WORK,1,NUMBER)

      C      PPERFORM A FORWARD TRANSFORM ON THE DATA
      C      CALL FOR2D(2,N,1-1,WORK,NUMBER)
      C      HFAN OUT THE TRANSFORMED VALUES, CONVERT TO A POWER SPECTRAL
      C      DENSITY, FREQUENCY AVERAGE

      150 ISPE=1
      TOTAL=FLOAT(N(1))
      DELTATE=1.0/FLOAT(1RATE)
      FACTOR=2.0*1.143*DELTAT/TOTAL
      RMS2=PM*S**2
      DO 35 J=1,NAVG
      DELTAN=FLOAT(ILIMIT(1,J))/(TOTAL*DELTAT)
      XLLIMIT(1,J)=DELTAN
      LIMIT(3,J)=LIMIT(2,J)/LIMIT(1,J)
      35 XLLIMIT(2,J)=LIMIT(3,J)*DELTAN
      DO 36 J=2,NAVG
      XLLIMIT(2,J)=XLIMIT(2,J)+XLIMIT(2,J-1)
      36 XLIMIT(2,J)=XLIMIT(2,J)+XLIMIT(2,J-1)
      WRITE(6,2004)(XLIMIT(1,J)*XLIMIT(1,J)*XLIMIT(1,J),J=1,NAVG)
      2003 FORMAT(//,*10X,*SCHEME OF VARIABLE BANDWIDTH SPECTRUM SMOOTHING*)
      2004 FORMAT(10X,*UPPER LIMIT COS *F10.2*5X,*HANDWIDTH *F10.4)
      10OUTPUT POINT*,19.5X,*HANDWIDTH *F10.4)
      NREC=1
      K1=0
      DO 40 J=1,NAVG
      C      COMPUTE THE NUMBER OF RECORDS NECESSARY TO COMPUTE THIS PORTION
      C      OF THE SPECTRUM
      C
      235

```

```

J3=NUMHFR/LIMIT(1,J)
J2=LIMIT(1,J)
J1=LIMIT(2,J)/NUMBER
DELTN=FLOAT(J2)/(TOTAL*DELTAT)
J1=MFC+J1-1
DO 45 IENREC=J1
  CALL INREAD(2,I,WORK,1,NUMBER)
  DO 37 K=1,NUMBER
    WRITE(3,300) WORK(K)
    300 FORMAT(2E12.4)
    37 WORK(K)=FACTOR*(REAL(WORK(K))*2+ALMAG(WORK(K))**2)
    IADD=0
C   SMOOTH THE SPECTRUM USING VARIABLE BANDWIDTH TECHNIQUES
C
      DO 39 KK=1,J3
      DO 38 L=1,J2
        SPECT(IISP)=SPECT(IISP)+REAL(WORK(IADD+L))
      38 SPECT(IISP)=SPECT(IISP)/(FLOAT(J2)*RMS2)
        IF(IISP.EQ.1)FREQ(IISP)=+DELTN/2.0
        IF(IISP.EQ.1)GO TO 30
        IF(I.F0.NREC.AND..KK.EQ.1)FREQ(IISP)=FREQ(IISP-1)+DELTN/2.0+ODELTN/2.
10       IF((KK.EQ.1.AND..I.EQ.NREC)
          FREQ(IISP)=FREQ(IISP-1)+ODELTN
30       IADD=IADD+J2
39       ISP=ISP+1
45       CONTINUE
C   INTEGRATE THE SPECTRUM LEAVING OUT THE END PORTIONS
C
      XINC(J)=ODELTN
      60 KL=K1+LIMIT(3,J)
      63 CALL TPS(SPEC1,XINC(J),SUM,K1 LIMIT(3,J))
      XINT=XINT+SUM
      ODELTN=ODELTN
      NREC=J1+1
C   ADD ENDPOINTS AND OTHER ODD PRECISIONS
C
      INDE=1
      KL=NAV6+1
      DO 80 I4=1,KL
      71 IF((I4.NF.KL)GO TO 72
        XINT=XINT+XINC(I4)*SPECT(INF-1)/2.0
        GO TO 40
      72 XINT=XINT+SPECT(IND)*(XINC(I4)+XINC(I4-1))/2.0
      78 IND=IND+LIMIT(3,I4)
      80 CONTINUE
      80 WRITE(6,2003) XINT
      2008 FORMAT(1H0.10X,*INT AREA UNDER THE SPECTRUM IS *,F8.4)
C   OUTPUT THE SMOOTHED SPECTRUM
C
      WRITE(6,2001)
      M=IISP-1
240
245
250
255
260
265
270
275
280
285
290
295

```

```

      DO 50 J=1,M+4
      50 WHITE(6,2002)FRF(W(J)),SPECT(J),FREQ(J+1),SPECT(J+1),FREQ(J+2),SPECT
      1(J+2),FREQ(1,J+3),SPECT(J+3)
      2001 FORMAT(1H1,10X,*SMOOTHED SPECTRUM*,/,*10X,*FREQ CPS*,*10X,*G(N)*)
      2002 FORMAT(1E15.4)

C   C   PLOT THE SMOOTHED SPECTRUM

      CALL LOCAT(2RAT)
      CALL SET(1.50,9,25,1.75,12.95,0.01,1000.0,0,0,0000001,1.0,2,7,4)
      CALL PFPIM(5,0,7,0)
      CALL SYMBOL(3,5,-6,0,25,LAHX,0,0,40)
      CALL SYMBOL(-6,3,0,25,LAHY,90,0,40)
      CALL SYMBOL(1,0,3,5,2,KEY1,0,0,30)
      CALL SYMBOL(1,0,3,2,2,KEY2,0,0,30)
      CALL SYMBOL(1,0,2,4,2,KEY3,0,0,30)
      CALL SYMBOL(1,0,2,6,2,KEY4,0,0,30)
      CALL SYMBOL(1,0,2,3,2,KEY5,0,0,30)
      CALL SYMBOL(1,0,2,0,2,KEY6,0,0,30)
      CALL CURVE(FRFQ,SPECT,M,4,2)
      CALL FRAME
      END

```

305                   310                   315

PROGRAM CSPECT2 (INPUT=101B,OUTPUT=202B,TAPE5=INPUT,TAPE6=OUTPUT,  
1 TAPE2=513,TAPE3=513B,TAPE4=513B)

THIS PROGRAM WAS WRITTEN 11/75 BY R. AKAINS TO COMPUTE AND PLOT  
A COHERENCE FUNCTION USING SEGMENT AVERAGING AND READING THE  
SINGLE CHANNEL TRANSFORMS FROM A DISC DEVICE, TAPE2 AND TAPE3.  
SUBROUTINES CALLED (ALL PLOT SUBROUTINES ARE DESCRIBED IN THE  
CSU USERS MANUAL, 1975 EDITION)

5

10           AXIS - PLOT ROUTINE  
CURVE - PLOT ROUTINE  
LOCAT - PLOT ROUTINE  
PEN2 - PLOT ROUTINE  
RSTR - PLOT ROUTINE  
SET - PLOT ROUTINE  
SKIPF - TAPE CONTROL  
SYMROL - PLOT ROUTINE

15

20

INPUT VARIABLES ARE

IRATE - SAMPLE RATE OF ORIGINAL TIME SERIES  
NRUN - NUMBER OF RUNS  
NSEG - NUMBER OF SEGMENTS  
NSKIP1 - TAPE CONTROL PARAMETER  
NSKIP2 - TAPE CONTROL PARAMETER  
NUMBER - LENGTH OF EACH SEGMENT  
TITLE1 - LABEL FOR CHANNEL 1  
TITLE2 - LABEL FOR CHANNEL 2  
X - COMPLEX ARRAY STORING TRANSFORM OF CHANNEL 1  
XTIT - PLOT AXIS LABEL  
Y - COMPLEX ARRAY STORING TRANSFORM OF CHANNEL 2  
YTIT - PLOT AXIS LABEL

35

PROGRAM VARIABLES

A - FACTOR USED IN FREQUENCY AVERAGING  
COH - ARRAY STORING FREQUENCY AVERAGED COHERENCE  
DELTAN - FREQUENCY INCREMENT OF SPECTRA  
FREQ - ARRAY STORING FREQUENCY FOR COHERENCE  
IND - INDEX USED IN FREQUENCY AVERAGING  
NPLT - TOTAL NUMBER OF POINTS TO PLOT  
N2 - NUMBER/2  
GXY - SEGMENT AVERAGED CROSS SPECTRAL DENSITY  
SPEC1 - SINGLE CHANNEL SEGMENT AVERAGED SPECTRA CHANNEL 1  
SPEC2 - SINGLE CHANNEL SEGMENT AVERAGED SPECTRA CHANNEL 2  
TAPE UNITS USED  
TAPE2 - MASTER INPUT TAPE  
TAPE3 - DISC USED AS INPUT FOR CHANNEL 1  
TAPE4 - DISC USED AS INPUT FOR CHANNEL 2  
TAPE5 - INPUT FILE  
TAPE6 - OUTPUT FILE

40

45

50

55

COMMON FREQ(500),TITLE1(8),TITLE2(8),COH(500),GXY(500),  
1SPEC1(500),SPEC2(500),X(4096),Y(4096),  
COMMON X(4096),Y(4096),COMPLEX GXY

```

60      COMPLEX X,Y
       C READ INPUT VARIABLES FOR ALL RUNS
65      READ(5,500)NRUN
       READ(5,500)IRATE,NUMBER,NSEG
       READ(5,502)XTIT,YTIT
       CALL PENZ(SHBLACK,4HFELT)
       CALL LOCAT(2RAT)
       ICODE=1
       DO 100 KTOT=1,NRUN
100      C ZERO NECESSARY ARRAYS
110      DO 111 I=1,500
           SPEC1(I)=0.0
           SPEC2(I)=0.0
           COH(I)=0.0
           GXY(I)=(0.0,0.0)
111      C READ INPUT VARIABLES FOR EACH RUN
120      READ(5,501)TITLE1,TITLE2
       READ(5,500)NSKIP1,NSKIP2
       FORMAT(31I0)
130      C READ INPUT VARIABLES FOR EACH RUN
140      READ(5,501)FORMAT(8A10)
       502      FORMAT(4A10)
       DELTAN=FLOAT(IRATE)/FLOAT(NUMBER)
150      C COPY INPUT ARRAYS FROM TAPE TO DISCS
160      REWIND 3
       REWIND 4
       DO 3 I=1,NSEG
       READ(2)X
       READ(2)Y
3      C WRITE(3)X
       BACKSPACE2
       CALL SKIPF(2,NSKIP1,17B,1)
       DO 4 I=1,NSEG
       READ(2)Y
       WRITE(4)Y
4      C BACKSPACE2
       CALL SKIPF(2,NSKIP2,17B,1)
       REWIND 3
       REWIND 4
170      C COMPUTE AND SEGMENT AVERAGE SINGLE CHANNEL SPECTRA AND
       CROSS SPECTRAL DENSITY
180      DO 30 JT=1,NSEG
       READ(3)X
       READ(4)Y
       DO 20 I=1,10
           SPEC1(I)=SPECT1(I)*CABS(X(I+1))**2
           SPEC2(I)=SPECT2(I)*CABS(Y(I+1))**2
           GXY(I)=GXY(I)+CONJG(X(I+1))*Y(I+1)
20      IND=11
       DO 22 K=11,49,3
       DO 21 J=1,3

```

```

120      SPECT1(IND)=SPECT1(IND)+CABS(X(K+J))**2
121      SPECT2(IND)=SPECT2(IND)+CABS(Y(K+J))**2
122      IND=IND+1
123      N2=NUMBER/2-25
124      DO 25 I=50,N2,20
125      J=1,20
126      SPECT1(IND)=SPECT1(IND)+CABS(X(I+J))**2
127      SPECT2(IND)=SPECT2(IND)+CABS(Y(I+J))**2
128      GXY(IND)=GXY(IND)+CONJG(X(K+J))*Y(K+J)
129      IND=IND+1
130      CONTINUE
131
132      C      SET UP THE FREQUENCY ARRAY
133      C      A=FLOAT(NSEG)
134      C      COMPUTE AND FREQUENCY AVERAGE THE COHERENCE FUNCTION
135      C
136      DO 35 I=1,10
137      GXY(I)=GXY(I)/A
138      COH(I)=(CABS(GXY(I))**2)*(A**2)/(SPECT1(I)*SPECT2(I))
139      FREQ(I)=FLOAT(I)*DELTAN
140      IND=11
141      A=3.0*A
142      DO 36 I=11,49,3
143      GXY(IND)=GXY(IND)/A
144      COH(IND)=(CABS(GXY(IND))**2)*(A**2)/(SPECT1(IND)*SPECT2(IND))
145      FREQ(IND)=(FLOAT(I+2)*DELTAN
146      IND=IND+1
147      A=20.0*A/3.0
148      DO 37 I=50,N2,20
149      GXY(IND)=GXY(IND)/A
150      COH(IND)=(CABS(GXY(IND))**2)*(A**2)/(SPECT1(IND)*SPECT2(IND))
151      FREQ(IND)=(FLOAT(I+5.5)*DELTAN
152      IF(FREQ(IND).GT.250.0)GO TO 60
153      IND=IND+1
154      NPLOT=IND-1
155
156      C      OUTPUT COHERENCE
157      WRITE(6,610)TITLE1,TITLE2
158      DO 50 I=1,NPLOT,3
159      WRITE(6,611)FREQ(I),COH(I),FREQ(I+1),COH(I+2)
160      610 FORMAT(6X,3(F9.2*8X,F7.4*7X),
161      12*,8A10//,6X,3(*FREQUENCY (HZ) COHERENCE
162      PLOT COHERENCE
163
164      CALL SET(1.0*6.0*1.0*6.0*0.0*300.0*0.0*2.0*1.0,-1.0,1)
165      CALL AXIS(0.0*0.0*XTIT,-4.0*6.0*0.0*0.0*50.0,-1)
166      CALL SYMBOL(3.0*6.0*1.0*TITLE1*0.0*0.0*2.0,2,1)
167      CALL SYMBOL(3.0*5.8*0.1*TITLE2*0.0*0.0*80.0)
168      CALL CURVE(FREQ,COH,NPLOT,0,0)
169      CALL RSTRT(ICODE)
170      ICODE=ICODE+1
171      GO TO(100,90)ICODE
172      90 ICODE=0
173      100 CONTINUE
174      END

```

PROGRAM CSPECT3(INPUT,OUTPUT,TAPE5=INPUT,TAPE6=OUTPUT,TAPE2,TAPE3,  
1TAPE4)

THIS PROGRAM WAS WRITTEN 11/75 BY R. AAKINS TO COMPUTE AND PLOT  
CROSS-CORRELATION FUNCTIONS USING SEGMENT AVERAGING AND READING  
THE SINGLE CHANNEL TRANSFORMS FROM A DISC DEVICE, TAPE 2 AND TAPE 3.  
SUBROUTINES CALLED (ALL PLOT SUBROUTINES ARE DESCRIBED IN THE  
CSU USERS MANUAL, 1975 EDITION)

10                   AXIS - PLOT ROUTINE  
CURVE - PLOT ROUTINE  
FOURT - FFT ROUTINE  
FRSTPT - PLOT ROUTINE  
LOCAT - PLOT ROUTINE  
PENZ - PLOT ROUTINE  
ROTATE - PLOT ROUTINE  
RSTR - PLOT ROUTINE  
SET - PLOT ROUTINE  
SKIPF - TAPE CONTROL SUBROUTINE - CSU USERS MANUAL  
SYMBOL - PLOT ROUTINE  
VECTOR - PLOT ROUTINE

15                   INPUT VARIABLES ARE

20                   IRATE - SAMPLE RATE OF INITIAL TIME SERIES  
NRUN - NUMBER OF RUNS  
NSEG - NUMBER OF SEGMENTS  
NSKIP1 - TAPE CONTROL PARAMETER  
NSKIP2 - TAPE CONTROL PARAMETER  
NUMBER - LENGTH OF SINGLE CHANNEL TRANSFORMS  
TITLE1 - CHANNEL 1 TITLE  
TITLE2 - CHANNEL 2 TITLE  
XTIT - PLOT TITLE X-AXIS  
YTIT - PLOT TITLE Y-AXIS

25                   INPUT VARIABLES

30                   IRATE - FREQUENCY STEP OF X,Y,GXY

35                   DELTAT - TIME STEP OF CROSS-CORRELATION  
FACTOR - USED TWICE - FACTOR IN CROSS-SPECTRUM CALCULATION AND LATER  
CROSS CORRELATION CALCULATIONS  
GXY - COMPLEX ARRAY WITH SEGMENT AVERAGED CROSS SPECTRUM  
INDEX - USED IN OUTPUT AND PLOTTING  
N2 - NUMBER/2  
R12 - REAL ARRAY STORING CROSS-CORRELATION FUNCTION

40                   TIME - REAL ARRAY WITH TIME LAGS USED IN OUTPUT

45                   X - COMPLEX ARRAY STORING TRANSFORM OF CHANNEL 1 TIME SERIES  
Y - COMPLEX ARRAY STORING TRANSFORM OF CHANNEL 2 TIME SERIES

50                   TAPE UNITS USED

55                   TAPE2 - MASTER INPUT TAPE  
TAPE3 - DISC USED AS INPUT FOR CHANNEL 1  
TAPE4 - DISC USED AS INPUT FOR CHANNEL 2  
TAPE5 - INPUT FILE  
TAPE6 - OUTPUT FILE

```

60      DIMENSION TIME(137),R12(137),TITLE1(4),TITLE2(4),XTIT(4),YTIT(4)
COMMON GXY(8192),X(4096),Y(4096)
COMPLEX GXY
COMPLEX X,Y

65      C   READ INPUT VARIABLES FOR ALL RUNS
       C   READ(5,500)NRUN
       C   READ(5,500)IRATE,NUMBER,NSEG
       C   READ(5,502)XTIT,YTIT
       C   CALL LOCAT(2,RAT)
       C   CALL PENZ(5HBLACK,4HFELT)
       C   ICODE=1
       DO 100 KLIN=1,NRUN
       DO 1  I=1,4096
          GXY(I)=0.0,0.0
1      C   READ INPUT VARIABLES WHICH CHANGE EACH RUN
       C   READ(5,501)TITLE1,TITLE2
       C   READ(5,500)NSKIP1,NSKIP2
       C   500  FORMAT(3I10)
       C   501  FORMAT(4A10)
       C   502  FORMAT(4A10)
       C   DELTAN=FLOAT(IRATE)/FLOAT(NUMBER)
       C   DELTAT=1.0/FLOAT(IRATE)
85      C   COPY INPUT ARRAYS X AND Y FROM DATA TAPE TO SEPARATE DISC FILES
       C   REWIND3
       C   REWIND4
       DO 3  I=1,NSEG
       C   READ(2)X
       C   WRITE(3)X
       C   BACKSPACE2
       C   CALL SKIPF(2,NSKIP1,178+1)
       DO 4  I=1,NSEG
       C   READ(2)Y
       C   WRITE(4)Y
       C   BACKSPACE2
       C   CALL SKIPF(2,NSKIP2,178+1)
       REWIND3
       REWIND4
90      C   CALCULATE SEGEMNT AVERAGED CROSS SPECTRAL DENSITY FUNCTION
       DO 30 JT=1,NSEG
       C   READ(3)X
       C   READ(4)Y
       DO 30 J=1,4096
       C   GXY(J)=GXY(J)+CONJG(X(J))*Y(J)
       30  FACTOR=2.0*1.43/FLOAT(JRATE)/FLOAT(NUMBER)
       DO 32 I=1,4096
       C   GXY(I)=FACTOR*GXY(I)
       32  GXY(I)=FACTOR*GXY(I)

100     C   REFLECT THE CROSS SPECTRAL DENSITY FUNCTION
       C   NDOUB=NUMBER
       C   N2=NUMBER/2
110     C
115     C

```

```

120      GXY(N2+1)=CONJG(GXY(N2))
      DO 33 I=1,4095
      K=NUMBER-I+1
      33 GXY(K)=CONJG(GXY(I+1))

      C      PERFORM A FORWARD TRANSFORM TO OBTAIN THE CROSS-CORRELATION FUNCTION
      C      CALL FOURT(GXY,NDOUB,1,1,1,0)
      C      FACTOR=FLOAT(IRRATE)/2.0/FLOAT(NUMBER)

      C      PLACE SELECTED VALUES OF THE CROSS-CORRELATION FUNCTION INTO ARRAY
      C      R12 AND ASSOCIATED TIME LAGS INTO ARRAY TIME FOR OUTPUT AND
      C      PLOTTING

      C      R12(69)=GXY(1)*FACTOR
      C      TIME(69)=0.0
      INDEX=1
      135    DO 34 I=1,20
      K=69+INDEX
      L=69-INDEX
      R12(K)=GXY(I+1)*FACTOR
      R12(L)=GXY(NUMBER-I+1)*FACTOR
      TIME(K)=DELTAT*FLOAT(I)
      TIME(L)=-TIME(K)
      INDEX=INDEX+1
      34    INDEX=1=22,60,2
      140    K=69+INDEX
      L=69-INDEX
      R12(K)=GXY(I+1)*FACTOR
      R12(L)=GXY(NUMBER-I+1)*FACTOR
      TIME(K)=DELTAT*FLOAT(I)
      TIME(L)=-TIME(K)
      INDEX=INDEX+1
      35    INDEX=1=65,200,5
      K=69+INDEX
      L=69-INDEX
      R12(K)=GXY(I+1)*FACTOR
      R12(L)=GXY(NUMBER-I+1)*FACTOR
      TIME(K)=DELTAT*FLOAT(I)
      TIME(L)=-TIME(K)
      INDEX=INDEX+1
      37    WRITE(6,610)TITLE1,TITLE2
      C      PRINT CROSS CORRELATION FUNCTION

      C      DO 39 I=1,137,2
      39    WRITE(6,611)TIME(I),R12(I)*TIME(I+1),R12(I+1)
      610   FORMAT(1H1,9X,*CROSS CORRELATION COEFFICIENT*,./,10X,*CHANNEL 1 -
      1*4A10*,10X,*CHANNEL 2 - *,4A10)
      611   FORMAT(1IX,F6.3,5X,F7.4)
      C      PLOT CROSS CORRELATION FUNCTION

      C      CALL ROTATE(90,0)
      CALL SET(1,8,-7,6,-4,0,8,-2,1,1,0)
      CALL AXIS(0,0,0,0,X,T,40,6,90,-2,4,1,1)
      CALL AXIS(0,0,0,0,Y,T,40,6,90,-2,0,2,1)
      CALL FRSTPT(0,0,0,2)
      CALL VECTOR(0,0,1)

```

```
CALL FIRSTPT( -4,0,0 )
CALL VECTOR( 4,0 )
CALL CURVE( TIME,R12,137,0,0 )
CALL SYMBOL( 0.5,5.0,1,TITLE1,0,40 )
CALL SYMBOL( 0.5,4.8,0.1,TITLE2,0,0,40 )
CALL RSTR(ICODE)
ICODE=ICODE+1
GO TO 100,90,ICODE
90 ICODE=0
CONTINUE
100 END
180
185
```